State-of-the-art of WCET (Worst-Case Execution Time) Estimation methods Focus on architectural analysis

Isabelle Puaut (firstname.lastname@irisa.fr)

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Outline

- Context: real-time systems
- Classes of WCET estimation techniques
 - Dynamic (measurement-based) methods
 - Static methods
- Static WCET estimation methods
 - Flow analysis
 - Computation
 - Hardware-level analysis
- Current research directions



Real-time systems





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Real-time systems

- Definition
 - Systems those correct behavior depends not only on the logical result of the computation but also on the time at which the result is produced
- Timing constraints on operations
 - Ex: Deadline = maximum delay between task arrival and task termination
- Note: Real-time is not real-fast





Classes of real-time systems

Soft real-time

- Missing a deadline decreases the quality of service of the system
- Ex: multimedia applications (VoD, etc.)

Hard real-time

- Timing constraints must hold under all circumstances
- Missing a deadline can cause catastrophic consequences
- Ex: nuclear power station, medical equipment, control in transportation systems, etc.



How do we know the timing is right?





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Temporal validation of real-time systems

Testing

- Input data + execution (target architecture, simulator)
- Necessary but not sufficient (coverage of scenarios)

• Schedulability analysis

- Hard real-time: need for guarantees in all execution scenarios, including the worst-case scenario
- Task models and schedulability analysis methods (70s ⇒ today)







Execution time



Execution Time



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WCET (Worst-Case Execution Time)

Definition

- Upper bound for executing an isolated piece of code
 - Code considered in isolation
 - WCET ≠ response time
- WCET = variable Ci in schedulability tests

Different uses

- Temporal validation: schedulability tests
- System dimensioning: hardware selection
- Optimization of application code: early in application design lifecycle



WCET: influencing elements



void f(int a) {
for (int i=0;i<10;i++) {
 if (a==1) X; else Y;
 }</pre>

- Sequencing of actions (execution paths)
 - Input data dependent
- Duration of every action on a given processor
 - Hardware dependent

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WCET Analysis

Computes upper bounds for the execution time of isolated pieces of code

Challenges in WCET estimation

•Safety (WCET ≥ any possible execution time) :

– confidence in schedulability analysis methods

•Tightness

 Overestimation ⇒ schedulability test may fail, or too much resources might be used

•The analysis cost should be reasonable SIRISA

WCET estimation methods

Dynamic methods

- Principle
 - Input data
 - Execution (hardware, simulator)
 - Timing measurement
- Generation of input data
 - User-defined: reserved to experts
 - Exhaustive

RISA

- Risk of combinatory explosion
- Automatic generation: genetic algorithms, etc.

Measurements are often unsafe





WCET estimation methods

Static analysis methods

- Principle
 - Analysis of program structure (no execution)
 - Computation of WCET from program structure
- Components
 - Flow analysis:
 - Determines possible flows in program
 - Low-level analysis (hardware-level)
 - Determines the execution time of a sequence of instructions (basic block) on a given hardware
 - Computation from results of other components
 - All paths need to be considered (safety)



Static WCET analysis methods





WCET estimation methods: terminating programs

Flow analysis: loop bounds

Maximum number of iterations of loops

for i := 1 to N do	Loop bound: N	
for j := 1 to i do	Loop bound: N	N ² executions
begin		
if c1 then A		
else B		
if c2 then C	(N+1)N executi	ons
else D	-2	0113
end		

Tight estimation of loop bounds: improves tightness



Flow analysis: Infeasible paths



Flow analysis: Infeasible paths

Path ABDEF is infeasible

Identification of infeasible paths: improves tightness



Determination of flow facts

Automatic (static analysis)

• Not decidable in general (equivalent to halting problem)

Manual: annotations

- Loop bounds: constants, or symbolic annotations
- Annotations for infeasible / mutually exclusive paths / relations between execution counts



Some numbers

Pgm	Time (s)	WCETorig	Time (s)	WCETff	#FF	-%
Crc	4.9	834159	6.65	833730	56	0
Inssort	0.16	31163	0.17	18167	7	42
Ns	6.09	130733	6.81	130733	8	0
Nsichneu	36.88	119707	435.70	41303	65280	65

Flow analysis using abstract execution [Gus06]



Static WCET analysis methods



WCET computation

Assumptions

- Simple architecture
 - Execution time of an instruction only depends on instruction type and operand
 - No overlap between instructions, no memory hierarchy

WCET computation techniques

- Tree-Based WCET computation
- WCET analysis using implicit path enumeration (IPET)

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Tree-based computation (1/3)

int x, p=0, i=0;

if(i%2) {
 p++;

} else {

i++;

} }

for(x=0;x<5;x++)

- Data structures
 - Syntax tree
 - control structures
 - Basic block
- Principle
 - Determination of execution time of basic block (low-level analysis)
 - Computation based on a bottom-up traversal of the syntax tree



Seq1

Loop [4]

lf

BB₃

Seq2

 BB_5

BB₄

BB₆

BB₀

BB₁

BB

Tree-based computation (2/3)

WCET(SEQ) S1;;Sn		WCET(S1) + + WCET(Sn)	
WCET(IF)	if(test) then else	WCET(test) + max(WCET(then) , WCET(else))	
WCET(LOOP)	for(;tst;inc) {body}	maxiter * (WCET(tst)+WCET(body+inc)) + WCET(tst)	





Tree-based computation (3/3)

Advantages

- Low computational effort
- Good scalability with respect to program size
- Good user feedback (source-code level)

Drawbacks

- Not compatible with aggressive compiler optimizations
- Expression of complex flow facts difficult (inter-controlstructure flow facts)



IPET (Implicit Path Enumeration Technique)



Integer Linear Programming (ILP)

- Constant: T_i Variable: f_i
- Objective function: max: $f_1T_1+f_2T_2+...+f_nT_n$
- Structural constraints

$$\forall bb_i : f_i = \sum_{a_j \in In(bb_i)} a_k \in Out(bb_i)$$

$$f_1 = f_7 = 1$$

Extra flow information

 $\forall bb_i \text{ in loop, } f_i \leq k \text{ (loop bound)}$

 $f_i + f_j \le 1$ (mutually exclusive paths – not in loop)

 $f_i \le 2 f_i$ (relations between execution freqs.)



IPET

Advantages

- Supports all unstructured flows (gotos, etc.)
- Supports all compiler optimizations, including the most aggressive ones

Drawbacks

- More time-consuming than tree-based methods
- Low-level user feedbacks (works at binary level)
- Annotations are hard to provide (need to know compiler optimizations)

Mostly used in commercial/academic tools RISA



Static WCET analysis methods



Low-level analysis

- Simple architecture
 - Execution time of an instruction only depends on instruction type and operands
 - No overlap between instructions, no memory hierarchy

• "Complex" architecture

- Local timing effects
 - Overlap between instructions (pipelines)
- Global timing effects
 - Caches (data, instructions), branch predictors
 - Requires a knowledge of the entire code



Low-level analysis: Pipeline

Principle : parallelism between instructions



• Inter basic-block





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Pipelining (simple-scalar)

• Intra basic block

- Reservation tables describing the usage of pipeline stages
- Obtained by WCET analysis tool or external tool (simulator)
- Inter basic-block: modification of computation step
 - Tree-based: specific addition operator
 - IPET: extra constraints in ILP problem (negative costs on edges)



Low-level analysis: caches (1/2)

Cache takes benefit of temporal and spatial locality





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Low-level analysis: caches (2/2)

- Cache: Good average-case performance, but predictability issues
- How to obtain safe and tight estimates?
 - Simple solution (all miss): overly pessimistic
 - Objective: predict if an instruction will (certainly) cause a hit or might (conservatively) cause a miss.
- Analyses based on abstract interpretation



Instruction cache analysis

- Computation of Abstract Cache States (ACS)
 - Contains all possible cache contents considering "all" possible execution paths
- 3 Analyses (Fixpoint computation)
 - Must, May and Persistence
 - Modification of ACS
 - Update: at every reference
 - Join: at every path merging point
- Instruction categorization from ACS
 - Always hit, Always miss, First miss, Not-classified



Must analysis

ACS contain all program lines guaranteed to be in the cache at a given point



May analysis

ACS contain all program lines that may be in the cache at a given point



Instruction cache analysis

- From ACS to classification
 - If in ACS_must: Always Hit
 - Else, if in ACS_Persistence: First Miss
 - Else, if not in ACS_May: Always Miss
 - Else Not Classified
- From classification to WCET (IPET)
 - For every BB_i: T_first_i, T_next_i
 - For every reference
 - Hit -> cache latency
 - Miss -> cache latency + memory latency
 - Objective function: max Σ (f_first_i * T_first_i + f_next_i * T_next_i)
 - New constraints:
 - $f_i = f_i first_i + f_next_i$ $f_i first_i \le 1$ (for a non nested loop)



Static WCET analysis methods



The bad news... Timing anomalies

Example: out-of-order execution

	Disp. Cycle	Instruction
А	1	LD r4,0(r3)
В	2	ADD r5, r4, r4
С	3	ADD r11, r10, r10
D	4	MUL r11, r11, r11
Е	5	MUL r13, r12, r12





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Low-level analysis Other hardware elements

Data caches

Extra issue: determination of addresses of data

Cache hierarchies

Management policies

Branch predictors

– Most complex predictors out of reach !



A method for every usage

Static WCET estimation

- Safety 🙂
- Pessimism 🛞
- Need for a hardware model oxtimes
- Trade-off between estimation time and tightness (tree-based / IPET) ^(C)

Measurement-based methods

- Safety ? Probabilistic methods
- Pessimism 😊
- Pessimisin I and the second s







WCET estimation tools

- Academic
 - Chronos
 - Vienna
 - Heptane
 - Otawa
 - Sweet

- Industrial
 - Bound-T
 - aiT
 - Rapitime



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Open issues

- Low-level analysis
 - Increase of hardware complexity / incomplete documentation
 - Timing anomalies, integration of sub-analyses
 - Analysis tools may be released a long time after the hardware is available



Research directions

- Multicore architectures
 - Shared hardware resources (busses, last-level caches) ⇒
 estimation of resource contention
 - Complexity
- Parallel applications
 - Not only execution time: synchronization/communication
- Design of efficient predictable hardware



Research directions

- Software-controlled hardware
 - Cache locking
 - Cache partitioning
 - Software-controlled branch prediction
- Worst-case oriented compilation
- Scalability of analyses
- Probabilistic analysis



Some pointers

Bibliography

- Survey paper in TECS, 2008
- Survey of cache analysis for WCET, LITES 2017
- Workshop on worst-case execution time analysis (2001..2017), in conjunction with ECRTS

Working group

 Timing Analysis on Code-Level (TACLe) http://www.tacle.eu



Questions?





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Backup slides



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Low-level analysis Data caches

- Extra issue: determination of addresses of data
- Means: abstract interpretation / DF analysis
 - Value analysis
 - Pointer analysis
- Results:
 - Superset of referenced addresses per instruction
- Example:
 - for (int i=0;i<N;i++) tab[i+j/z] = x;
 - Any address inside tab may be referenced per loop iteration (but only one)
 - Hard-to-predict reference (input-dependent)



Low-level analysis

Data caches

- Solutions (with some limitations)
 - Compiler-controlled methods: don't cache inputdependent data structures
 - Assume every potentially referenced address is actually referenced (2*N misses in example)
 - Cache Miss Equations (CME): for affine dataindependent loop indices



Execution time



Execution Time



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