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# Exécuter un programme en parallèle sur un processeur Many-core

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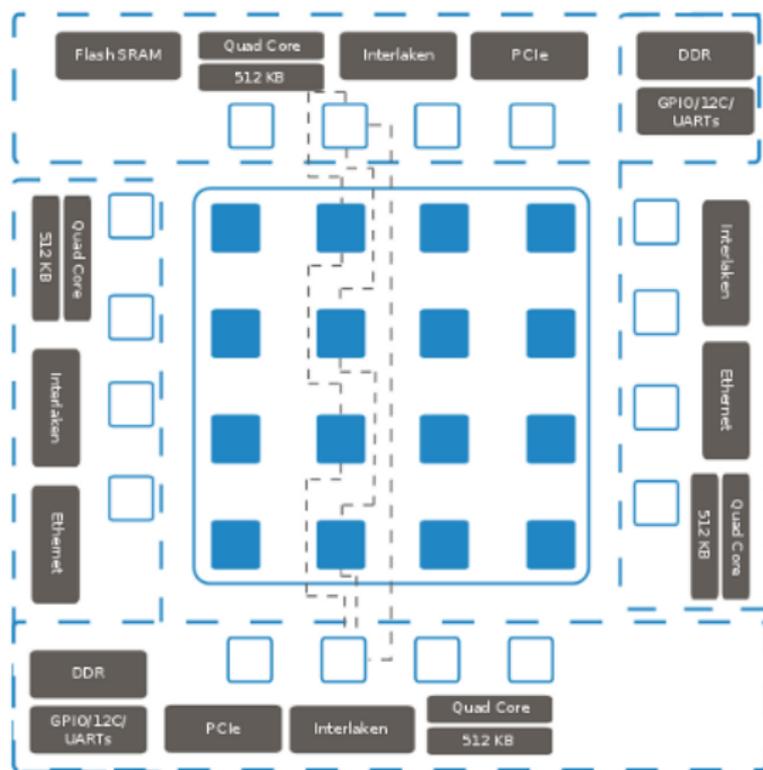
# Plan de la présentation.

- 1 Introduction.
- 2 L'exécution parallèle aujourd'hui.
- 3 Qu'est-ce qui séquentialise une exécution ?
- 4 Le parallélisme d'instruction.
  - L'élimination des fausses dépendances par le renommage.
  - L'élimination des vraies dépendances par la spéculation.
  - Exploitation du parallélisme proche par l'exécution spéculative et en désordre.
  - L'ILP distant.
  - Attraper le parallélisme d'instructions avec plusieurs cœurs.
- 5 Capturer l'ILP distant.
- 6 Conclusion.

## Un algorithme parallèle : la réduction de somme.

```
sum_reduce(t[0..n]) :  
  if n=2 then t[0] + t[1]  
  else sum_reduce(t[0..n/2]) + sum_reduce(t[n/2..n])
```

# Un processeur Many-core : le MPPA-256 de Kalray.



# Comment exécuter un algorithme en parallèle sur un Many-core ?

- Implémentation `pthread`, `MPI` ...

# Comment exécuter un algorithme en parallèle sur un Many-core ?

- Implémentation `pthread`, `MPI` ...
- Utiliser une bibliothèque de l'OS pour implémenter la `distribution`, la `communication` et la `synchronisation`.

# Une implémentation Pthread.

```
typedef struct{int *t; int n;} ST;
void *sum_reduce(void *st){
    unsigned int s,s1,s2;
    ST str1, str2;
    pthread_t tid1, tid2;
    if (((ST *)st)->n==2){
        return ((ST *)st)->t[0] + ((ST *)st)->t[1];
    }
    str1.t=((ST *)st)->t; str1.n=((ST *)st)->n/2;
    pthread_create(&tid1, NULL, sum_reduce, (void *)&str1);
    str2.t=((ST *)st)->t + ((ST *)st)->n/2; str2.n=((ST *)st)->n/2;
    pthread_create(&tid2, NULL, sum_reduce, (void *)&str2);
    pthread_join(tid1, (void *)&s1); pthread_join(tid2, (void *)&s2);
    s=s1+s2; pthread_exit((void *)s);
}
```

# Une implémentation MPI.

```
#include "mpi.h"  
...  
//i: local data element; s: recv, update (sum) and send s;  
MPI_Reduce(&i, &s, 1, MPI_INT, MPI_SUM, 0, MPI_COMM_WORLD);  
...
```

# Une implémentation pour GPU en CUDA.

```
--global-- void sum_reduce(int *t, int *sum){
    int tid = threadIdx.x;
    extern __shared__ s_data[];
    //to load the data from global memory to warp local shared memory
    s_data[tid] = ...;
    __syncthreads();
    for (int i=s_data_size; i>0; i/=2){
        if (tid < i){
            s_data[tid] = s_data[tid] + s_data[i+tid];
            __syncthreads();
        }
    }
    if (tid==0) sum[0]=s_data[0];
}
```

# Une implémentation en C.

```
(0) unsigned int sum_reduce(unsigned int t[], unsigned int n){  
(1)     if (n==2)  
(2)         return t[0]+t[1];  
(3)     else  
(7)         return  
(4)             sum_reduce(t, n/2)  
(6)         +  
(5)             sum_reduce(&t[n/2], n/2);  
(8) }
```

## Exécution du code C.

```
sum_reduce(&t[0], 8) =  
  (1) (3) (4)  
    sum_reduce(&t[0], 4)  
      (1) (3) (4)  
        sum_reduce(&t[0], 2)  
          (1) (2)  
      (5)  
        sum_reduce(&t[2], 2)  
          (1) (2)  
      (6) (7)  
  (5)  
    sum_reduce(&t[4], 4)  
      (1) (3) (4)  
        sum_reduce(&t[4], 2)  
          (1) (2)  
      (5)  
        sum_reduce(&t[6], 2)  
          (1) (2)  
      (6) (7)  
  (6) (7)  
trace = (1) (3) (4) (1) (3) (4) (1) (2) (5)  
        (1) (2) (6) (7) (5) (1) (3) (4) (1)  
        (2) (5) (1) (2) (6) (7) (6) (7)
```

# Qu'est-ce qui séquentialise l'implémentation C ?

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- Ce n'est pas le code C.
- C'est le modèle d'exécution employé : le modèle de Von Neumann.
- Ce modèle suppose l'existence d'un pointeur d'instruction IP contrôlant la phase d'extraction du programme enregistré en mémoire.

# Traduction du code C pour une architecture Von Neumann.

```
(01) sum_reduce:  pushq %rbx           #save t
(02)             pushq %rbp           #save n
(03)             subq  $8, %rsp       #allocate tmp
(04)             cmpq  $2, %rbp      #if (n!=2)
(05)             jne  .L2            #goto .L2
(06)             movq  8(%rbx), %rax  #a=t[1]
(07)             addq (%rbx), %rax    #a+=t[0]
(08)             jmp  .L3            #goto .L3
(09) .L2:        shrq  %rbp           #n=n/2
(10)             call sum_reduce     #a=sum(t, n/2)
(11)             movq %rax, 0(%rsp)   #tmp=a
(12)             leaq (%rbx,%rbp,8), %rbx #t=&t[n/2]
(13)             call sum_reduce     #a=sum(&t[n/2], n/2)
(14)             addq 0(%rsp), %rax   #a+=tmp
(15) .L3:        addq $8, %rsp       #free tmp
(16)             popq %rbp           #restore n
(17)             popq %rbx           #restore t
(18)             ret                  #return a
```

# Exécution du code assembleur.

```
sum_reduce(&t[0], 8) =  
7 (01)-(05), (09), (10)  
    sum_reduce(&t[0], 4)  
7 (01)-(05), (09), (10)  
    sum_reduce(&t[0], 2)  
12 (01)-(08), (15)-(18)  
3 (11)-(13)  
    sum_reduce(&t[2], 2)  
12 (01)-(08), (15)-(18)  
5 (14)-(18)  
3 (11)-(13)  
    sum_reduce(&t[4], 4)  
7 (01)-(05), (09), (10)  
    sum_reduce(&t[0], 2)  
12 (01)-(08), (15)-(18)  
    (11)-(13)  
    sum_reduce(&t[2], 2)  
12 (01)-(08), (15)-(18)  
5 (14)-(18)  
5 (14)-(18)  
90
```

trace = 90 instructions

# Le parallélisme d'instruction ou ILP.

- ILP **proche** du pointeur d'instruction (centaines d'instructions).

# Le parallélisme d'instruction ou ILP.

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- ILP **distant**, c-à-d K ou M ou G instructions.

- Il est contrecarré par les dépendances.

## L'ILP proche.

- Il est contrecarré par **les dépendances**.
- **Vraies** dépendances : producteur -> consommateur (données et contrôle).

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- **Vraies** dépendances : producteur -> consommateur (données et contrôle).
- **Fausse**s dépendances : ressources (registres et mémoire).

## Vraies dépendances sur l'exemple.

```
(01) sum_reduce:  pushq %rbx           # prod %rbx
(02)             pushq %rbp           # 01, prod %rbp
(03)             subq  $8, %rsp       # 02
(04)             cmpq  $2, %rbp       # prod %rbp
(05)             jne  .L2             # 04
(06)             movq  8(%rbx), %rax   # 05, prod %rbx, prod (%rbx)
(07)             addq (%rbx), %rax    # 05, 06, prod %rbx, prod (%rbx)
(08)             jmp  .L3             # 05
(09) .L2:        shrq  %rbp           # 05, prod %rbp
(10)             call sum_reduce      # 05, 02
(11)             movq %rax, 0(%rsp)   # 05, prod (%rsp), prod %rax
(12)             leaq (%rbx,%rbp,8), %rbx # 05, prod %rbx, prod %rbp
(13)             call sum_reduce      # 05, prod %rsp
(14)             addq 0(%rsp), %rax   # 05, prod %rsp, prod (%rsp)
(15) .L3:        addq $8, %rsp       # 02
(16)             popq %rbp           # 15, 02
(17)             popq %rbx           # 16, 01
(18)             ret                  # 17, prod (%rsp)
```

## Fausse dépendances sur l'exemple.

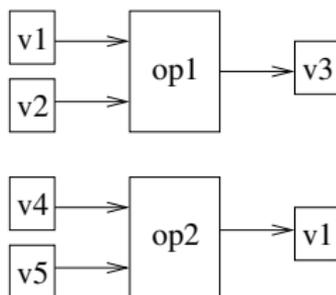
```
(01) sum_reduce:  pushq %rbx           # ecr en (%rsp), lec en (%rsp)
(02)             pushq %rbp           # ecr en (%rsp), lec en (%rsp)
(03)             subq  $8, %rsp       # 02
(04)             cmpq  $2, %rbp       # ecr en %eflags, lec en %eflag
(05)             jne   .L2            #
(06)             movq  8(%rbx), %rax   # ecr en %rax, lec en %rax
(07)             addq (%rbx), %rax     # 06
(08)             jmp   .L3            #
(09) .L2:        shrq  %rbp           # ecr en %rbp, lec en %rbp
(10)             call sum_reduce      # ecr en %rsp, lec en %rsp
(11)             movq %rax, 0(%rsp)   # ecr en (%rsp), lec en (%rsp)
(12)             leaq (%rbx,%rbp,8), %rbx # ecr en %rbx, lec en %rbx
(13)             call sum_reduce      # ecr en %rsp, lec en %rsp
(14)             addq 0(%rsp), %rax   # ecr en %rax, lec en %rax
(15) .L3:        addq $8, %rsp       # ecr en %rsp, lec en %rsp
(16)             popq %rbp           # ecr en %rbp, lec en %rbp
(17)             popq %rbx           # ecr en %rbx, lec en %rbx
(18)             ret                  #
```

# La duplication de l'espace par le renommage. Dépendances EAL.

$v3 = v1 \text{ op1 } v2$ $v1 = v4 \text{ op2 } v5$
--

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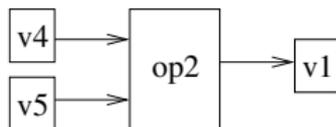
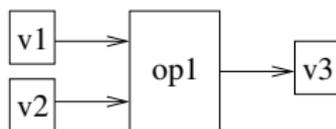
$v3 = v1 \text{ op1 } v2$   
 $v1 = v4 \text{ op2 } v5$



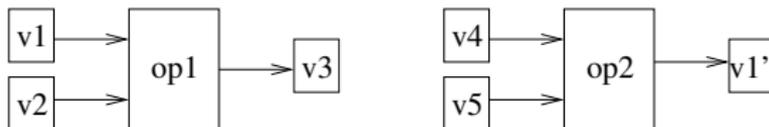
Sans renommage: 2 séquences

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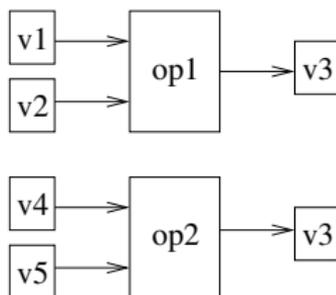
Avec renommage  $v1 \rightarrow v1'$ : 1 séquence

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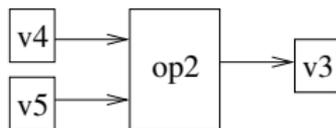
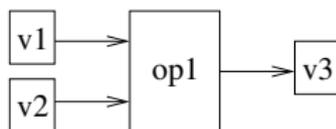
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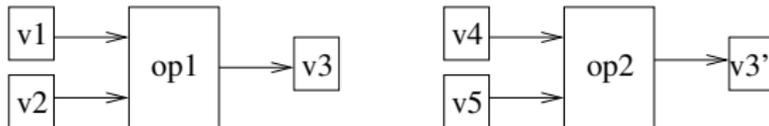
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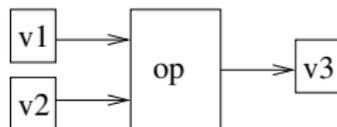
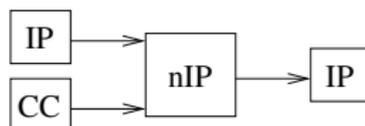
Avec renommage  $v3 \rightarrow v3'$ : 1 séquence

# La spéculation de la source (IP) par la prédiction de saut. Dépendances de contrôle.

```
    jne .L1  
.L1  v3 = v1 op v2
```

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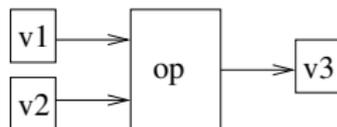
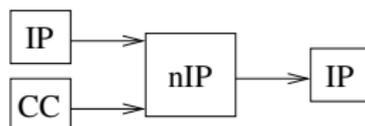
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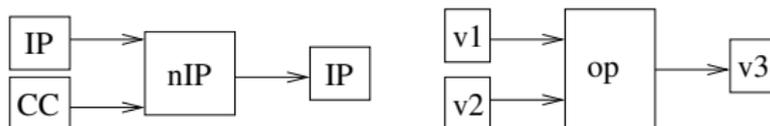
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Sans prédiction: 2 séquences



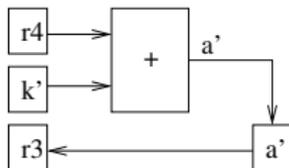
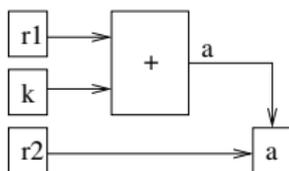
Avec prédiction: 1 séquence

# La spéculation de la source par son chargement anticipé. Dépendances de mémoire.

$$\begin{array}{l} m[r1+k] = r2 \\ r3 = m[r4+k'] \end{array}$$

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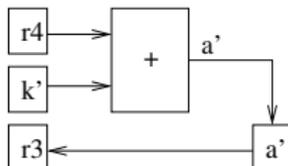
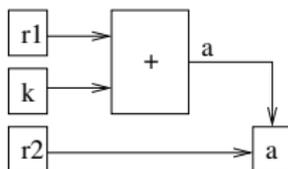
$$\begin{aligned} m[r1+k] &= r2 \\ r3 &= m[r4+k'] \end{aligned}$$



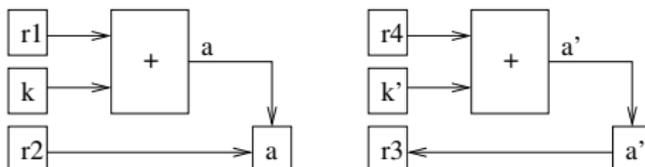
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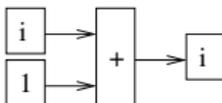
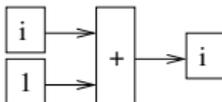
Avec spéculation: 1 séquence

## Le calcul au renommage. Dépendances de données.

$i = 0$
$i = i + 1$
$i = i + 1$

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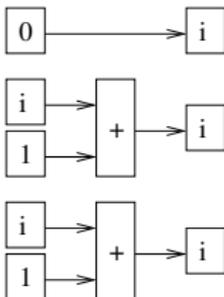
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Sans précalcul: 3 séquences

# Le calcul au renommage. Dépendances de données.

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```



Sans précalcul: 3 séquences

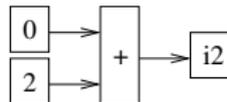
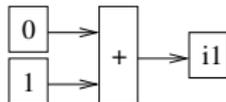
instruction  
renommage

$i = 0$   
 $i0 = 0$

$i = i + 1$   
 $i1 = 0 + 1$

$i = i + 1$   
 $i2 = 0 + 2$

exécution



Avec précalcul: 1 séquence

# Le partage de l'espace et l'élimination des copies. Dépendances de données.

```
mov v1, v2  
mov v2, v3  
mov v3, v4
```

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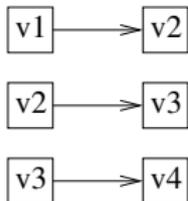
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Sans partage: 3 séquences

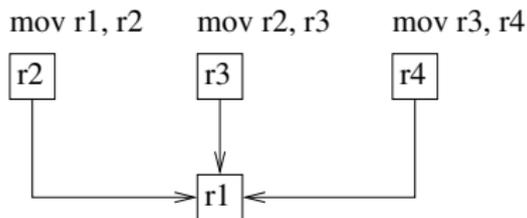
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Sans partage: 3 séquences

instruction  
renommage



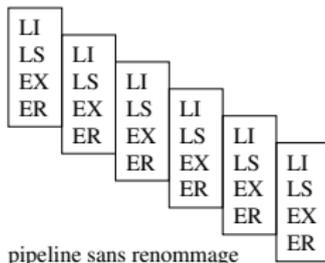
exécution

Avec partage: 0 séquence



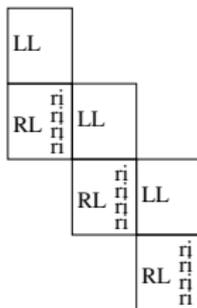
# Une phase de renommage.

lecture d'une instruction  
lecture de ses sources  
exécution  
écriture de ses résultats



lecture d'une ligne d'instructions

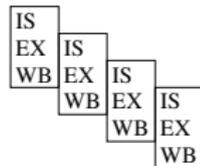
renommage d'une instruction



pipeline de renommage

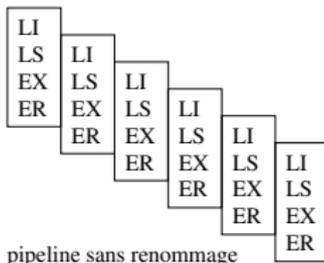
démarrage ooo des instructions prêtes  
exécution en parallèle  
terminaison

pipeline d'exécution ooo



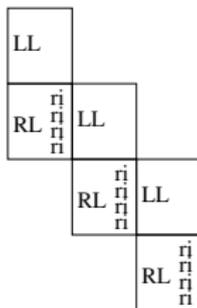
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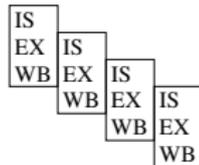
lecture d'une ligne d'instructions

renommage d'une instruction



démarrage ooo des instructions prêtes  
exécution en parallèle  
terminaison

pipeline d'exécution ooo



automate  
de lecture et  
de renommage

LI&R

instructions renommées

IP calculés

EX OOO

automate  
d'exécution  
ooo

# Un prédicteur de saut.

- Prédit les sauts conditionnels (direction et cible).

## Un prédicteur de saut.

- Prédit les sauts conditionnels (direction et cible).
- Prédit les sauts inconditionnels indirects (cible).

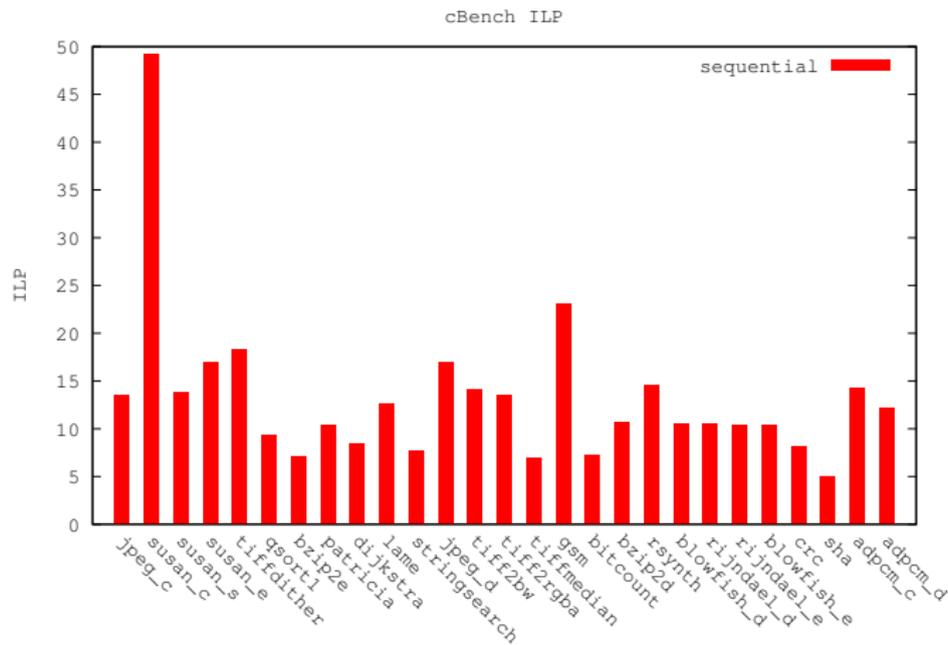
## Un prédicteur de saut.

- Prédit les sauts conditionnels (direction et cible).
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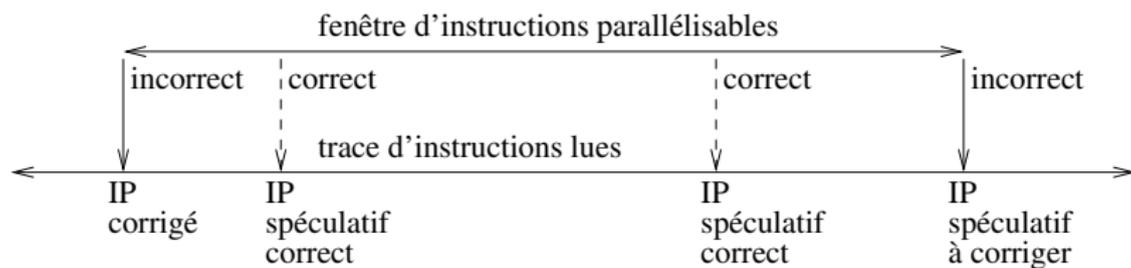
## Un prédicteur de saut.

- Prédit les sauts conditionnels (direction et cible).
- Prédit les sauts inconditionnels indirects (cible).
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- Taux de succès : 97%.

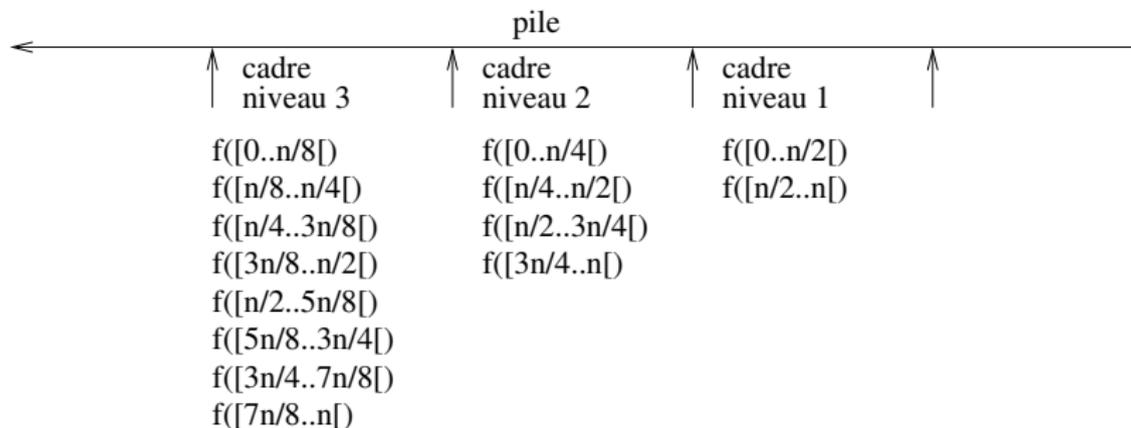
# Impact de la parallélisation par le renommage mémoire et la prédiction de saut.



## Premier verrou : séquentialisation par le contrôle.



## Second verrou : séquentialisation par la gestion de la pile.



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- On ne sait pas prédire une trace au delà de quelques centaines d'instructions mais
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- Le **point de retour** d'un appel de fonction.
- La **sortie d'une boucle**.

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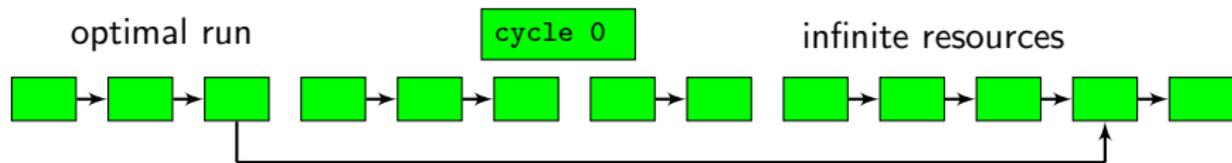
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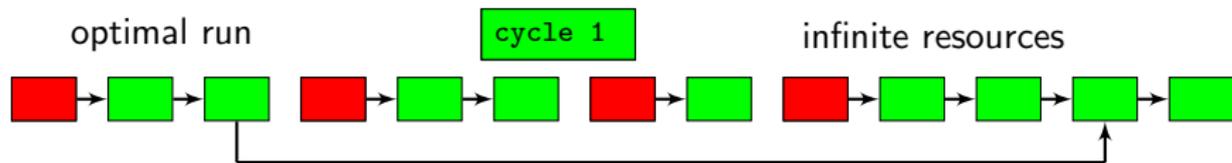
la position du pointeur de pile au retour est la même qu'à l'appel.

- **Spéculer** sur la position du pointeur de pile.
- **Distinguer** les cadres d'appels de même niveau par renommage.

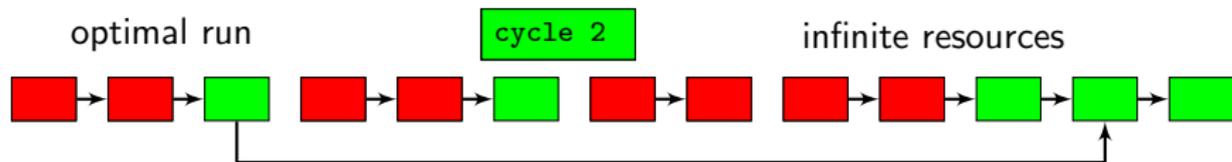
# How to capture distant ILP.



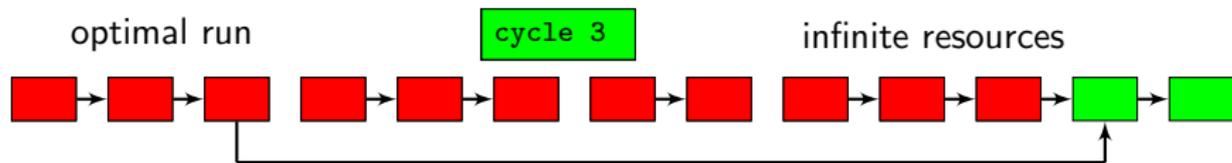
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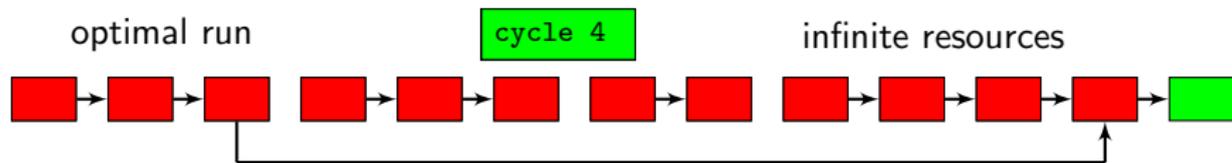
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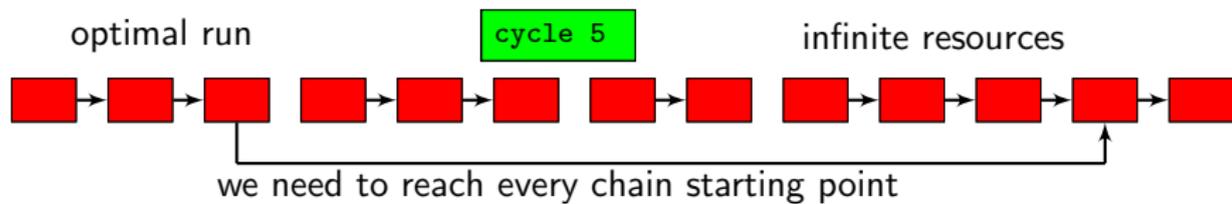
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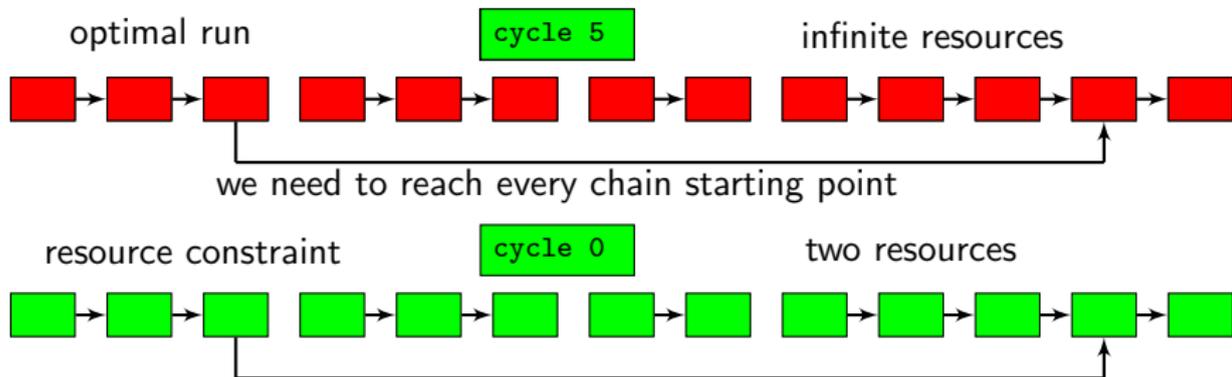
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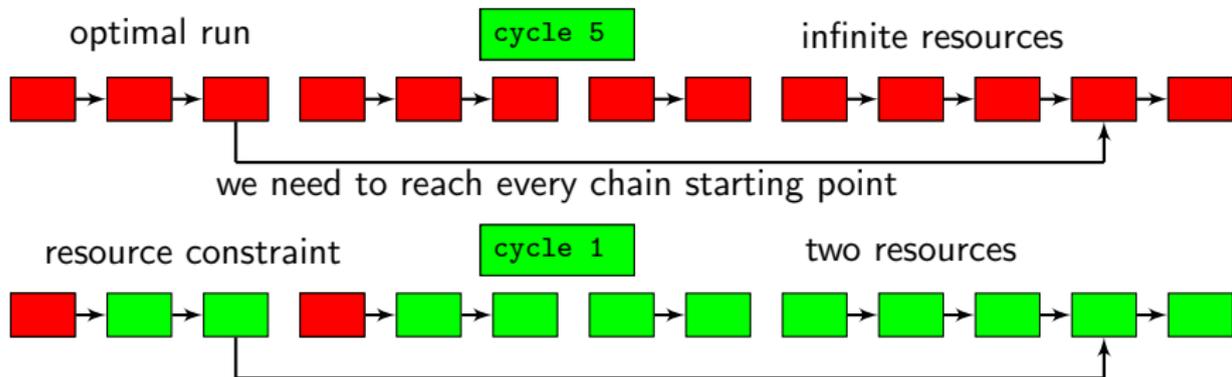
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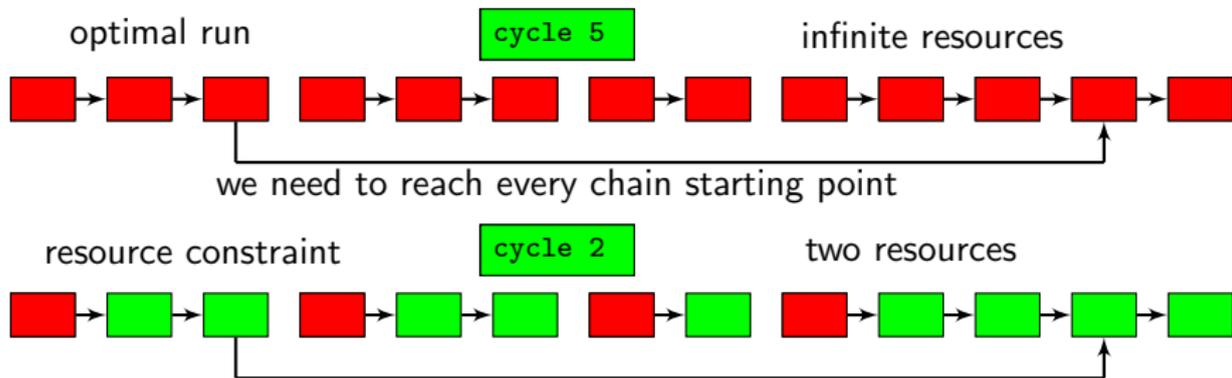
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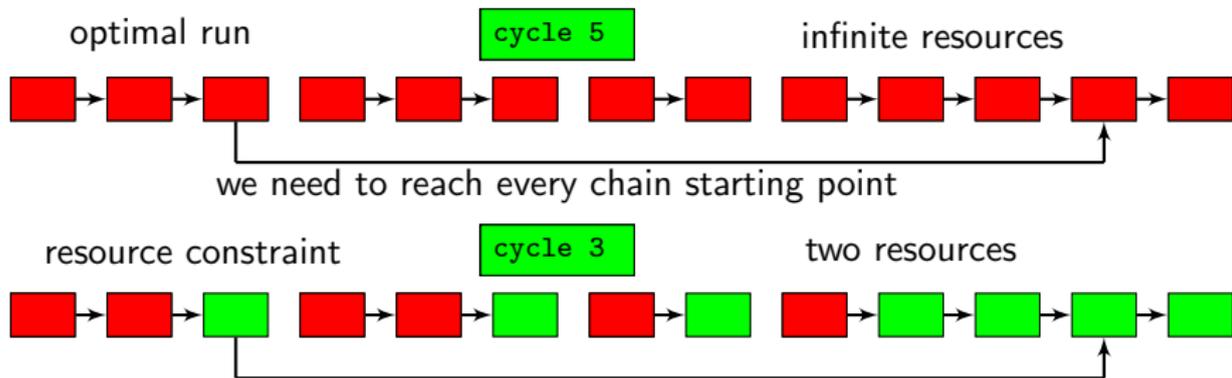
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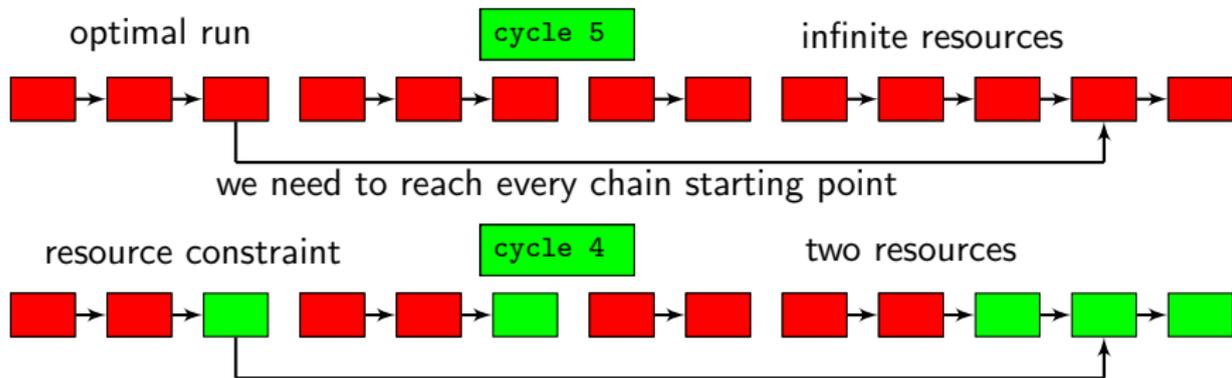
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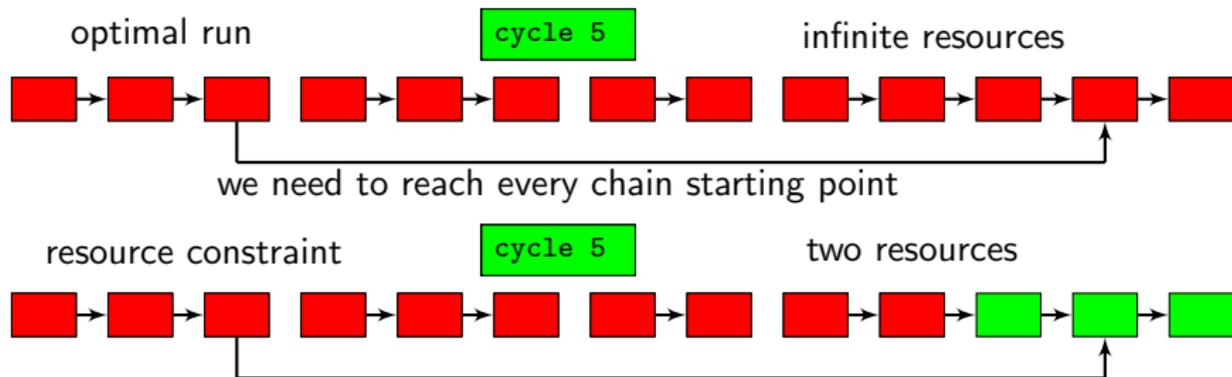
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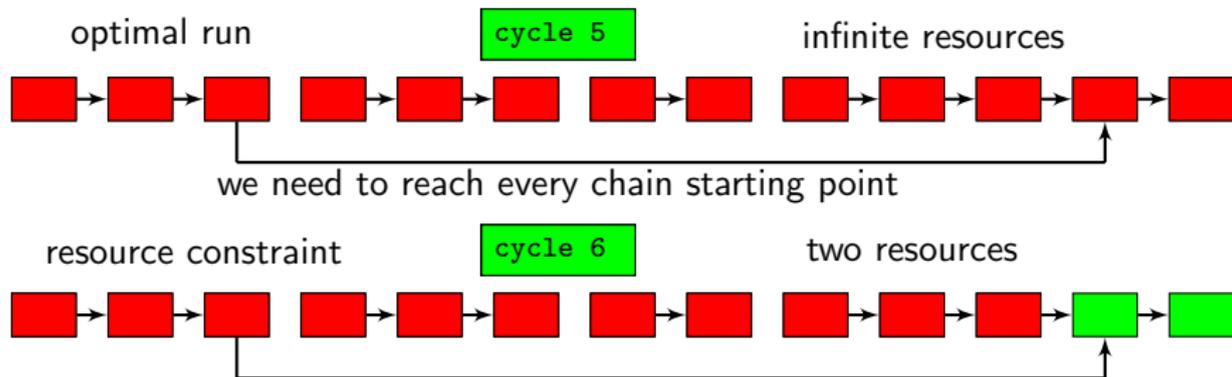
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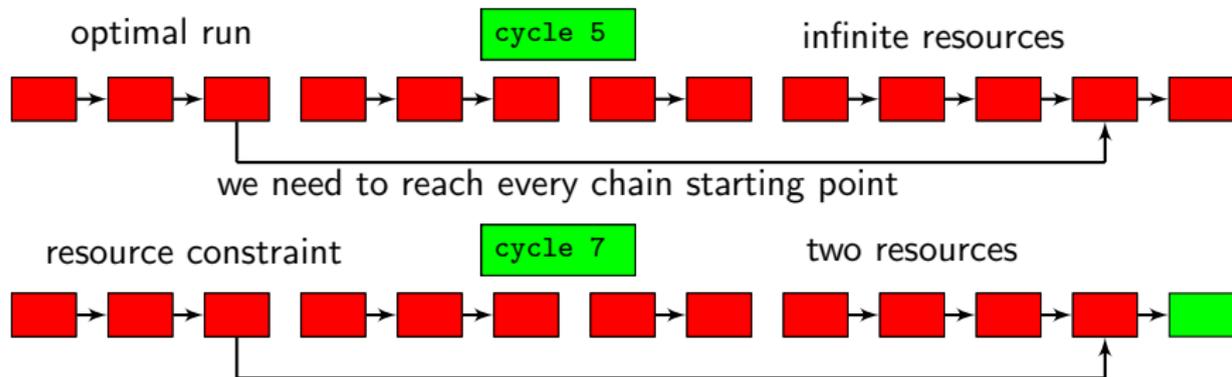
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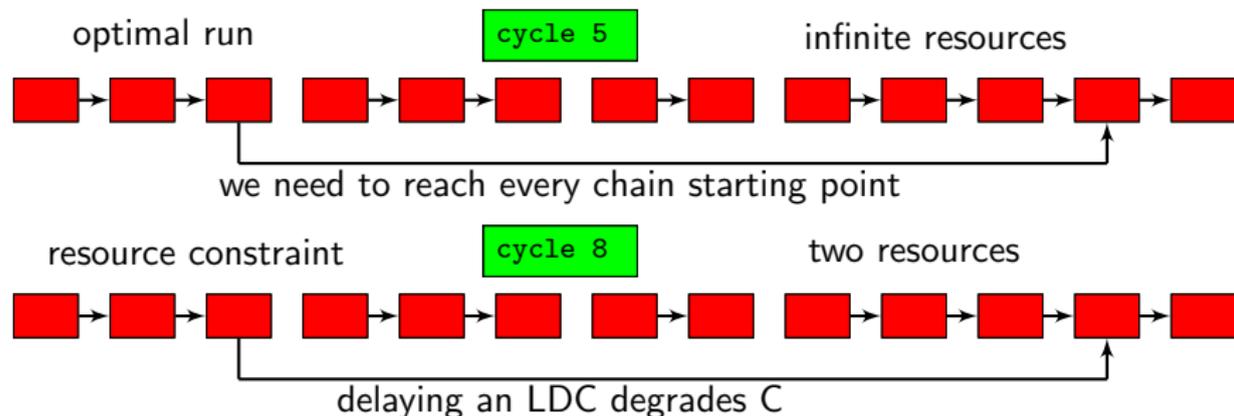
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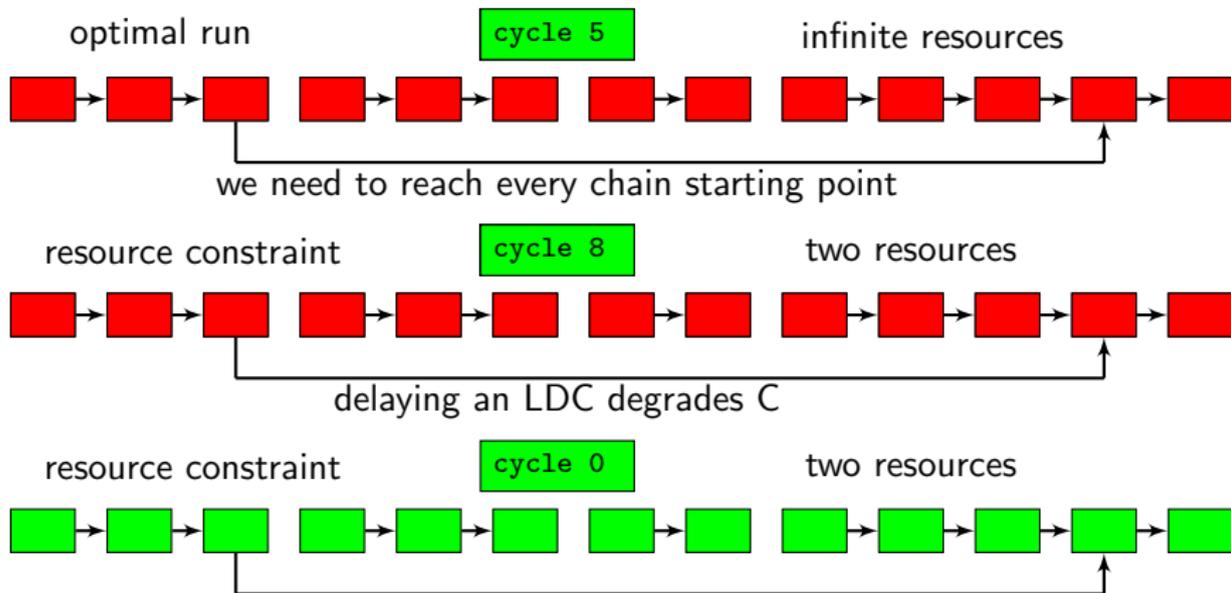
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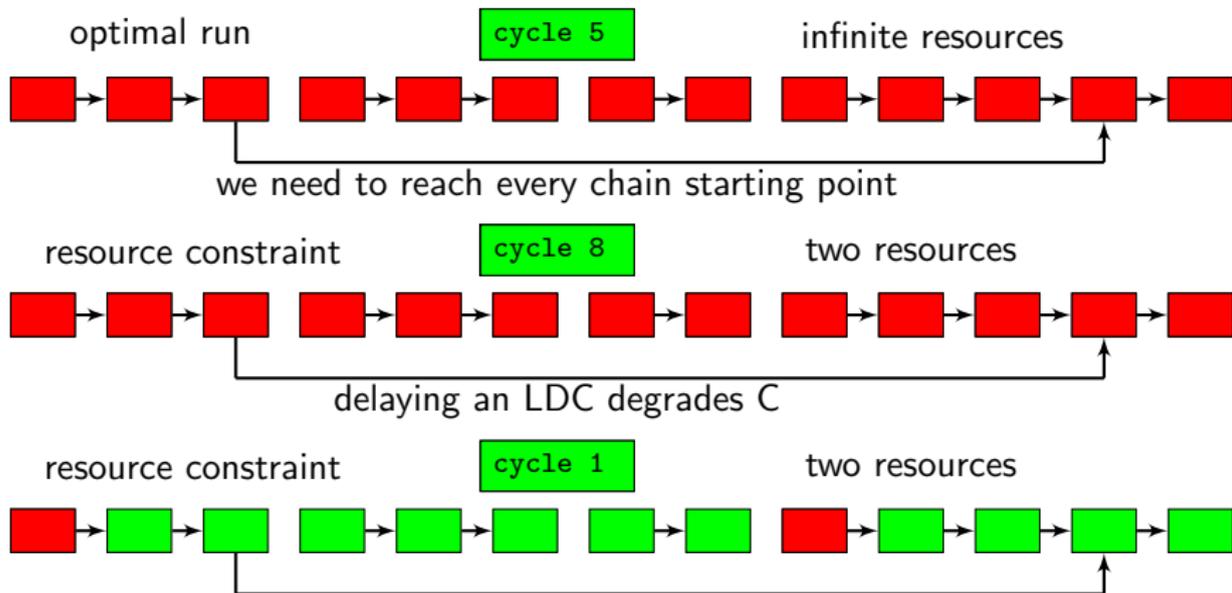
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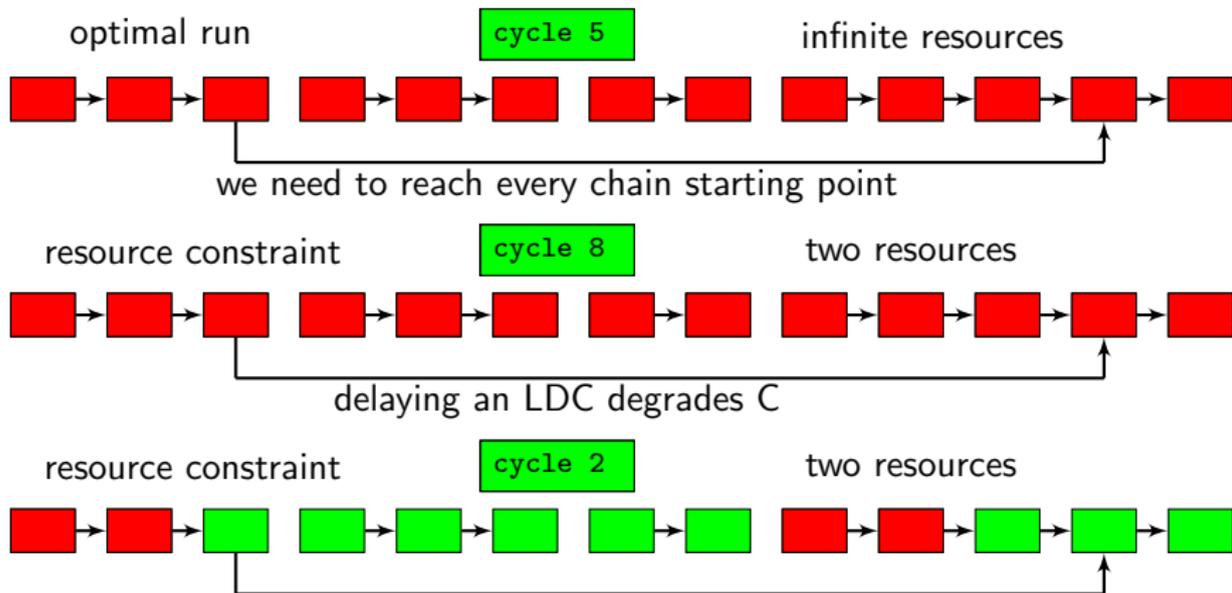
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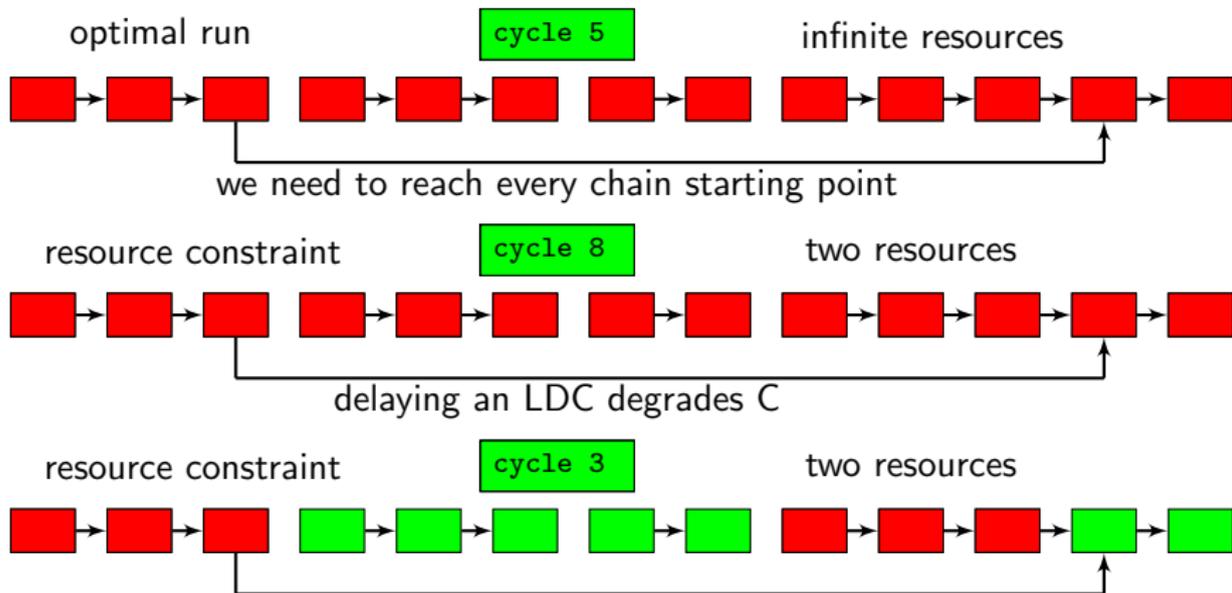
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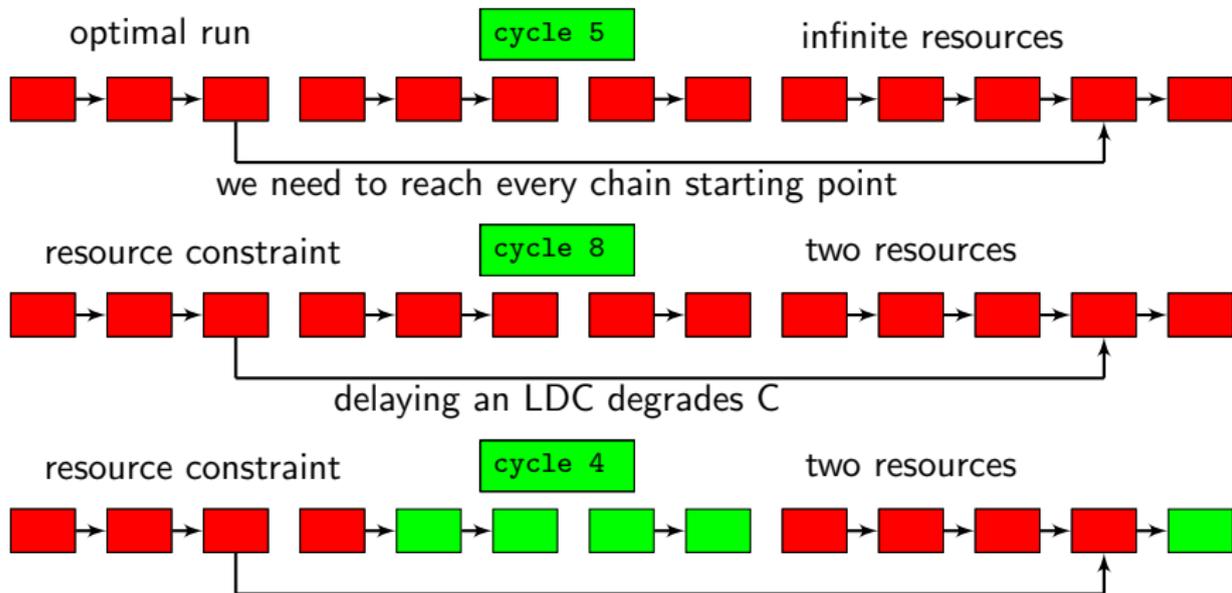
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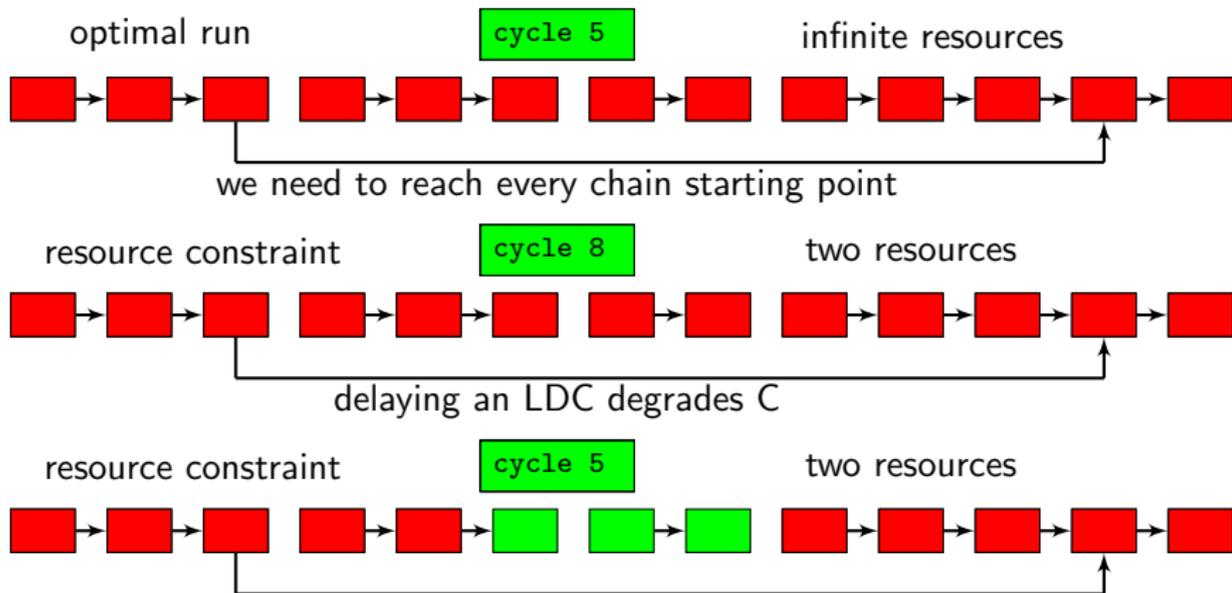
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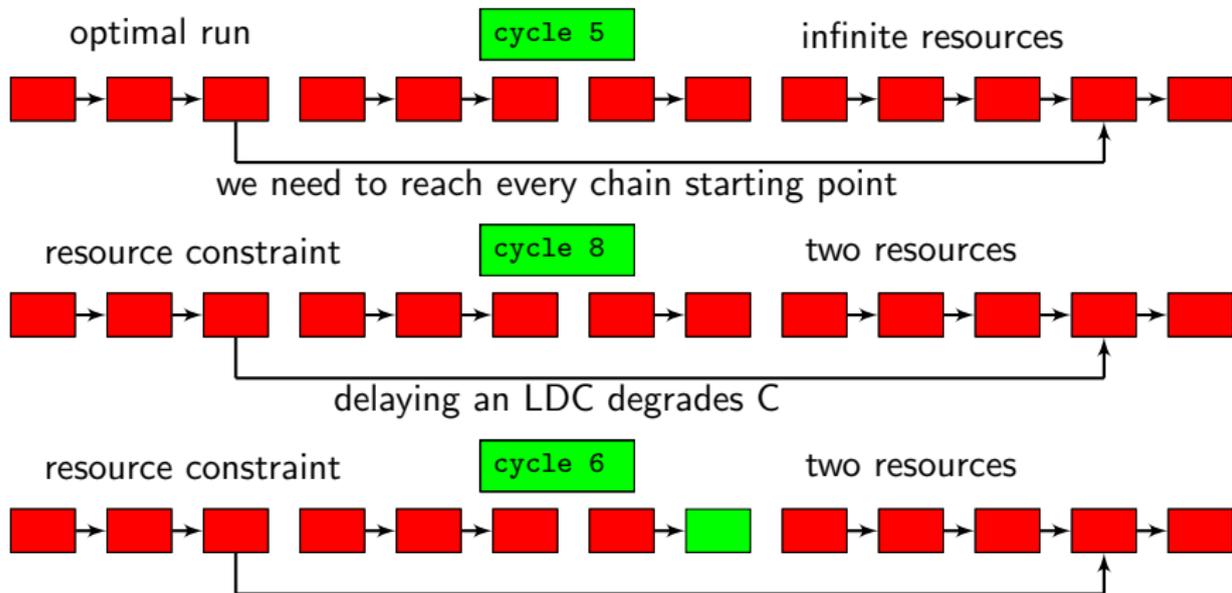
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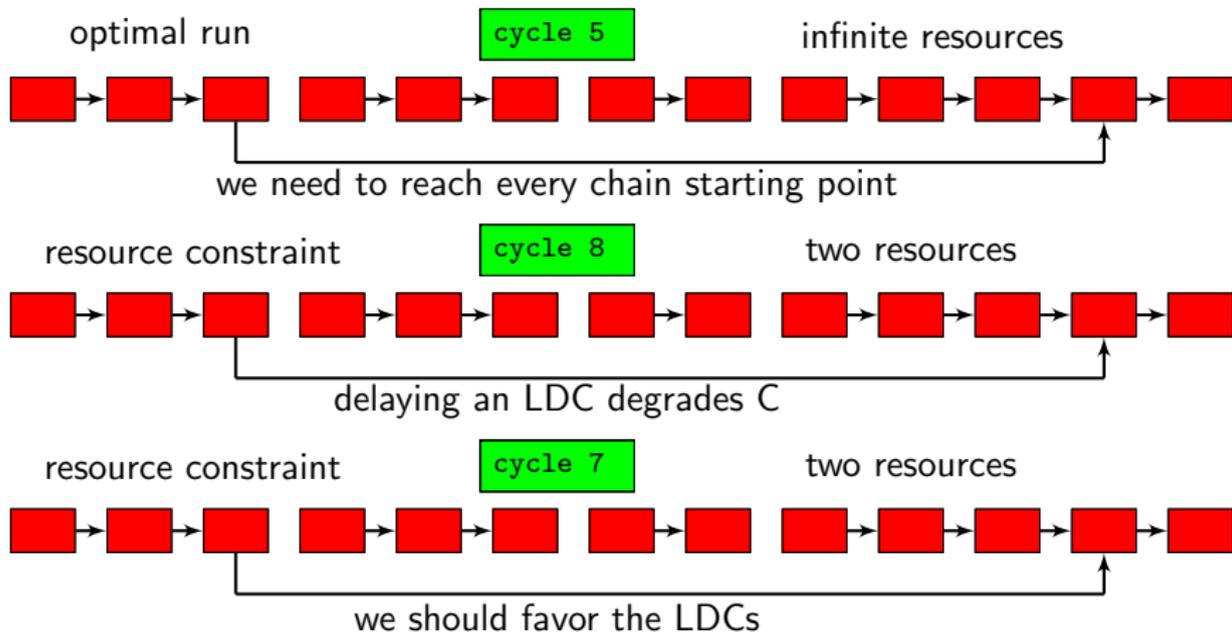
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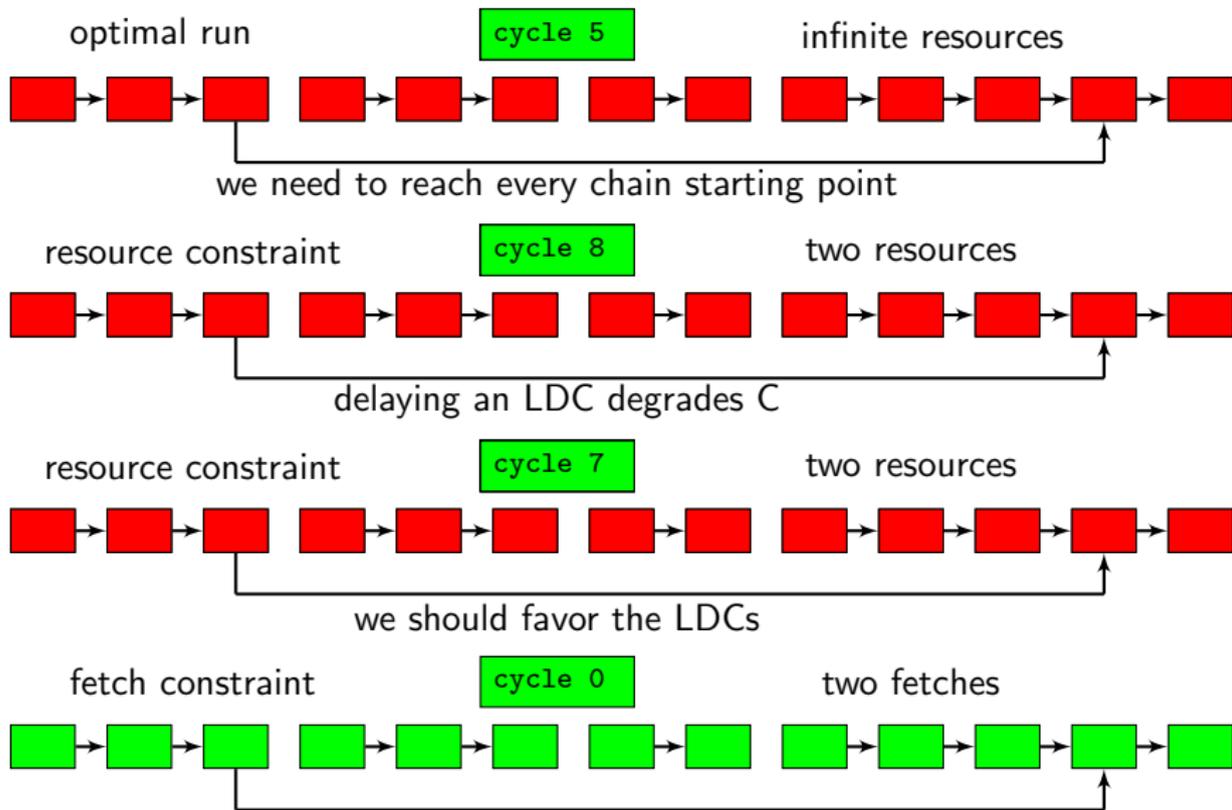
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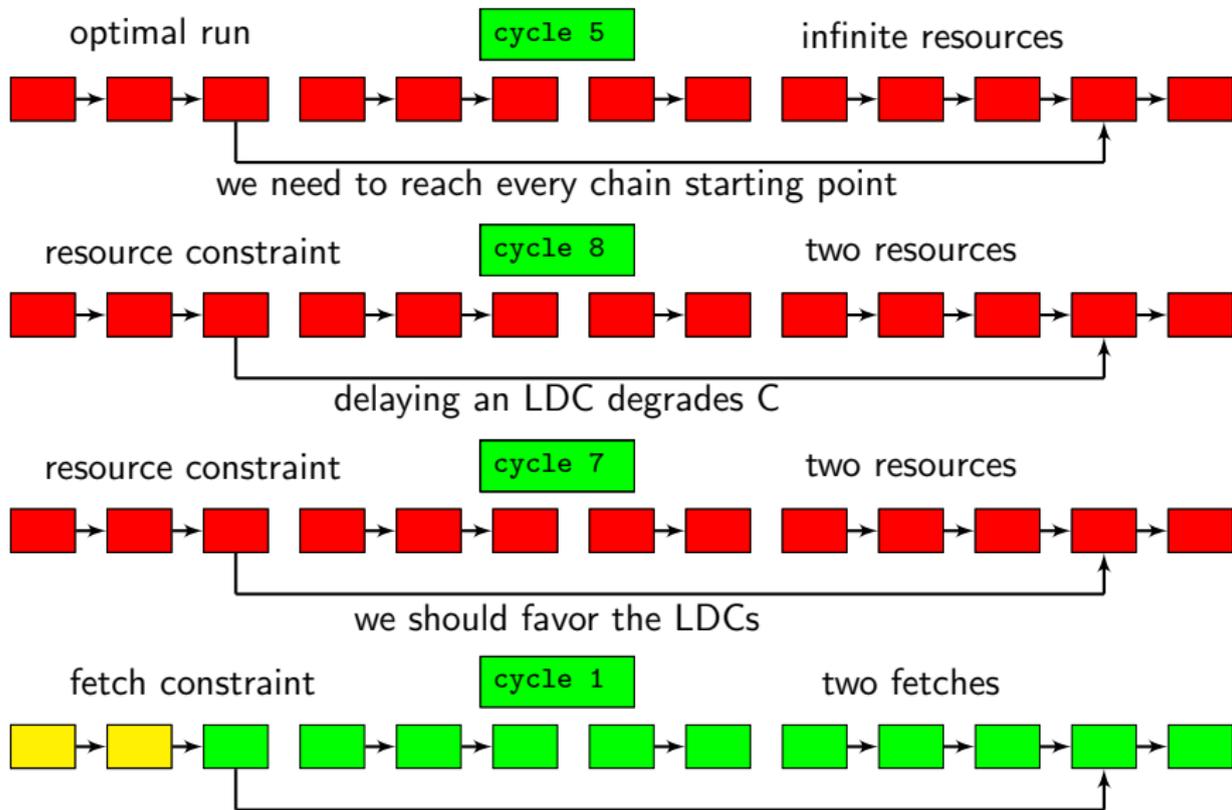
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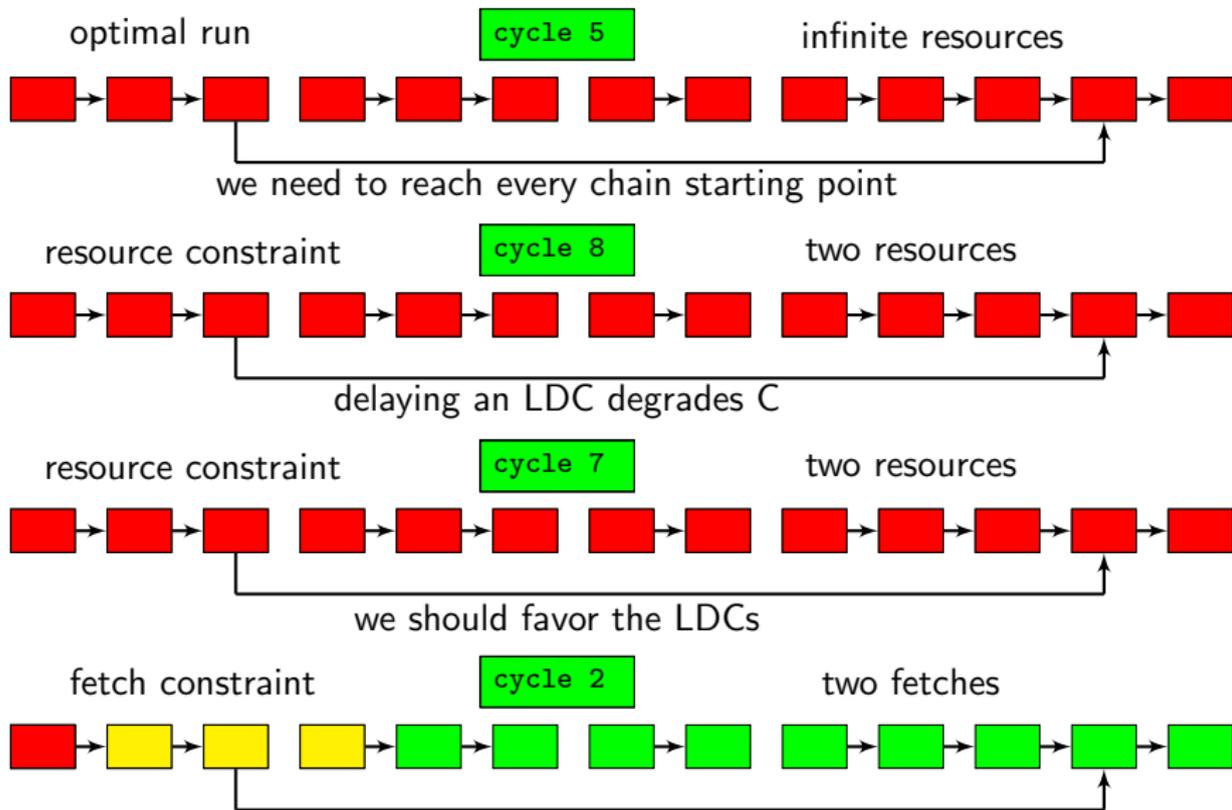
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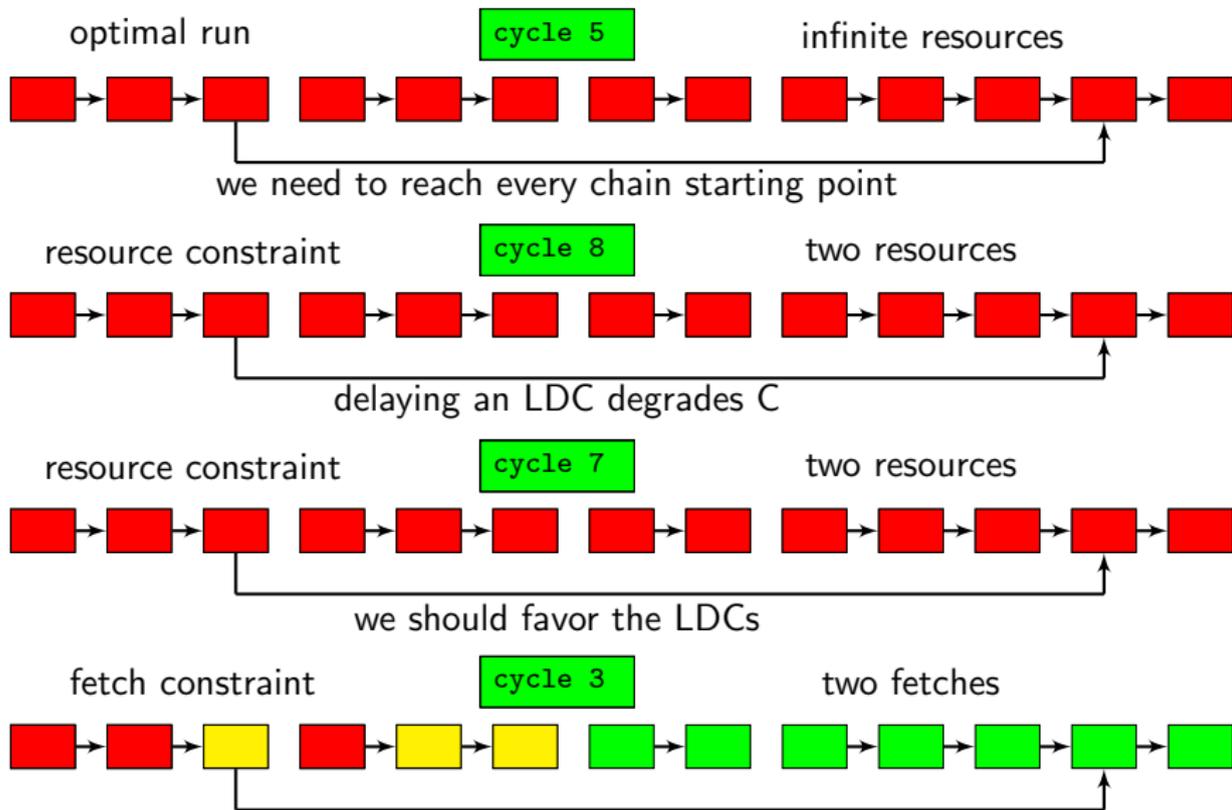
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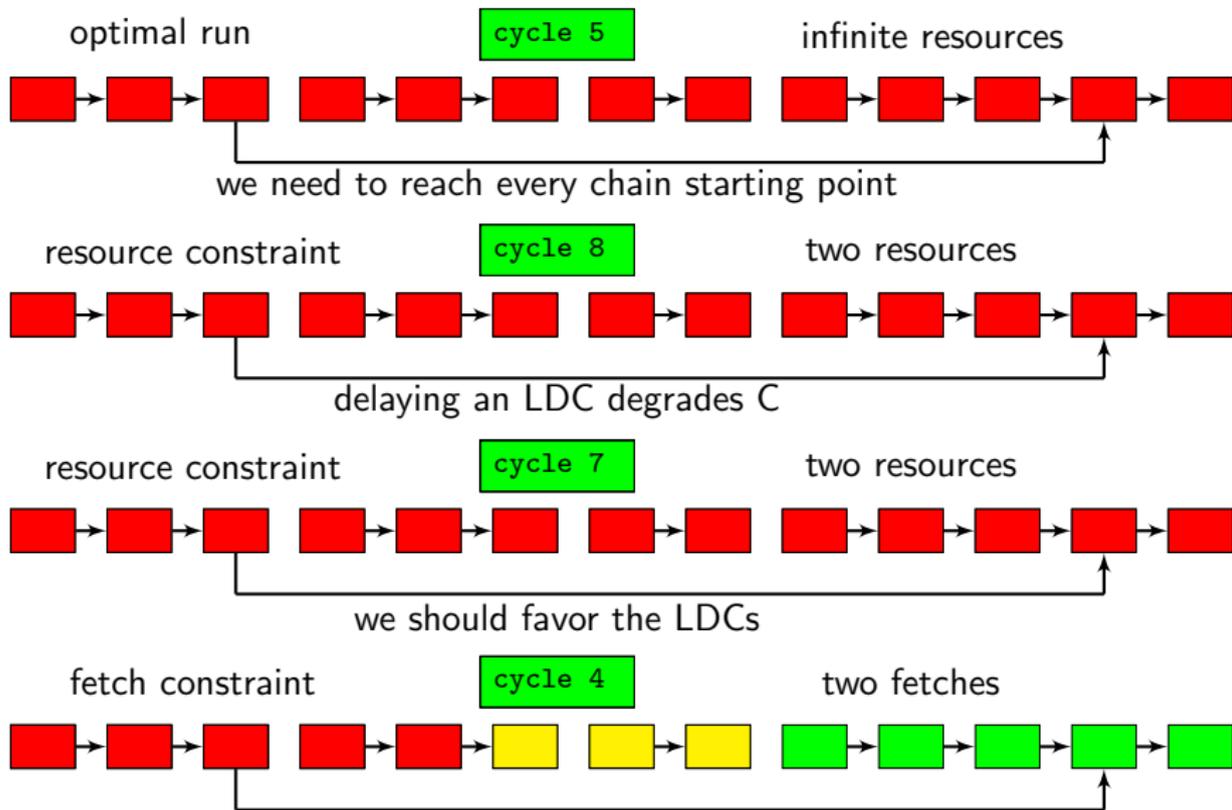
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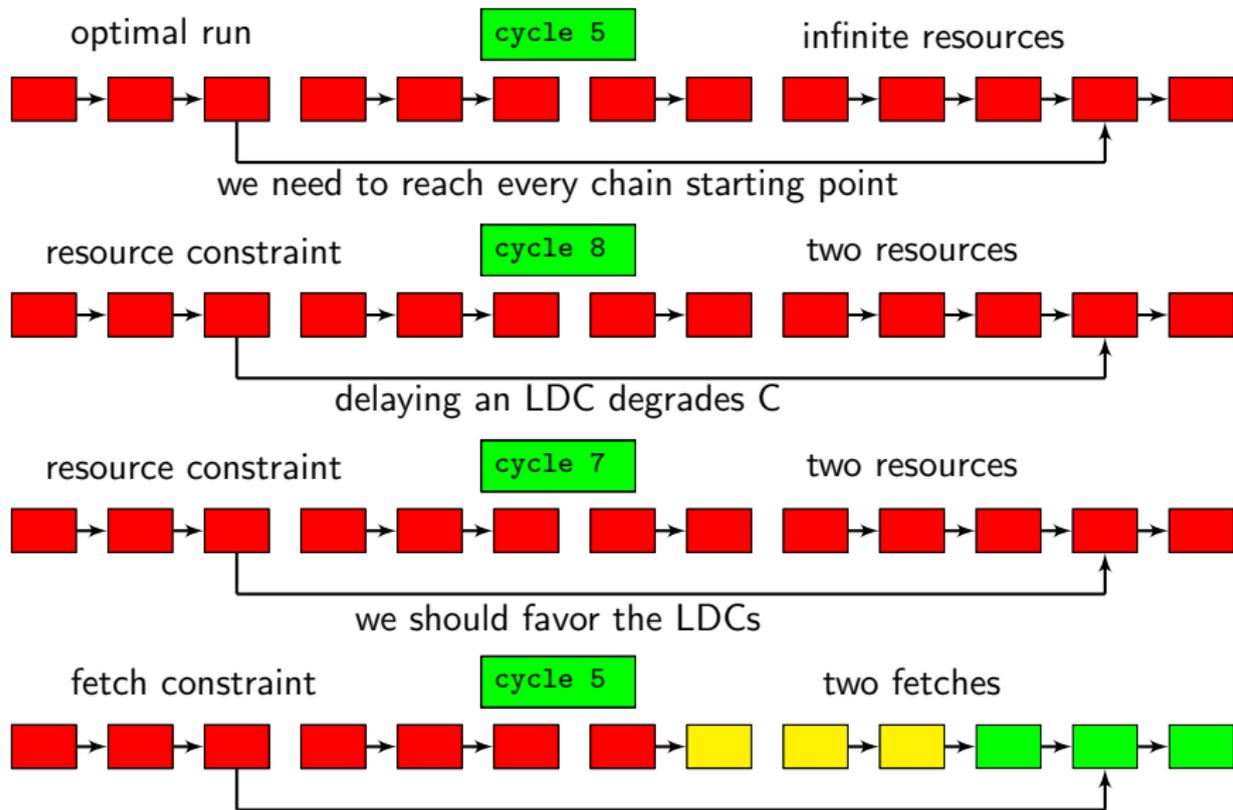
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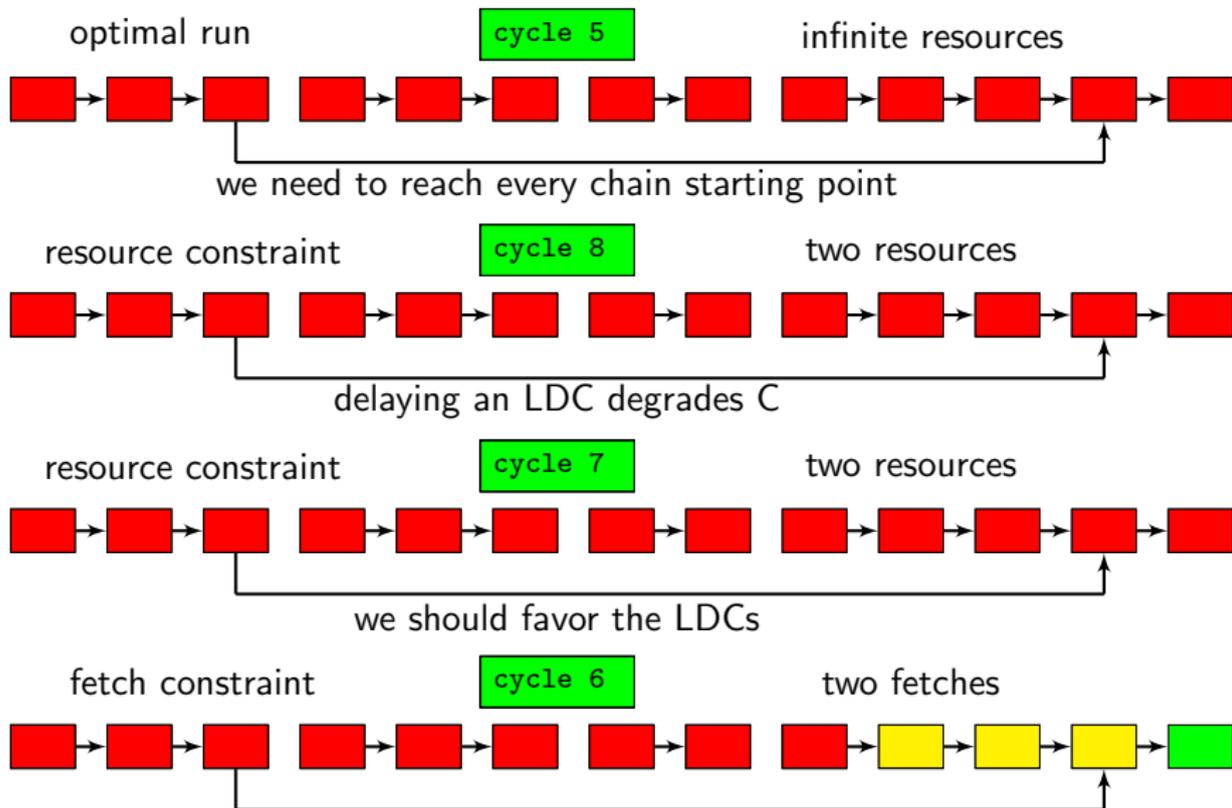
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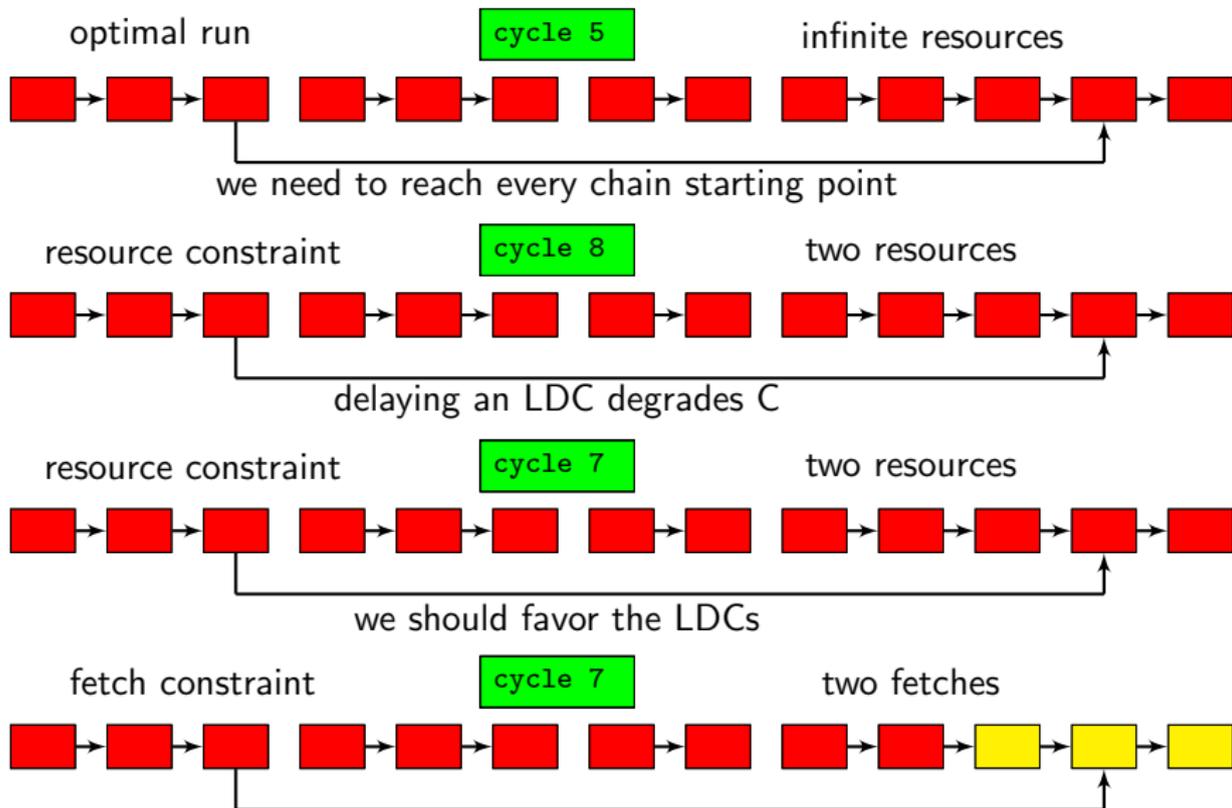
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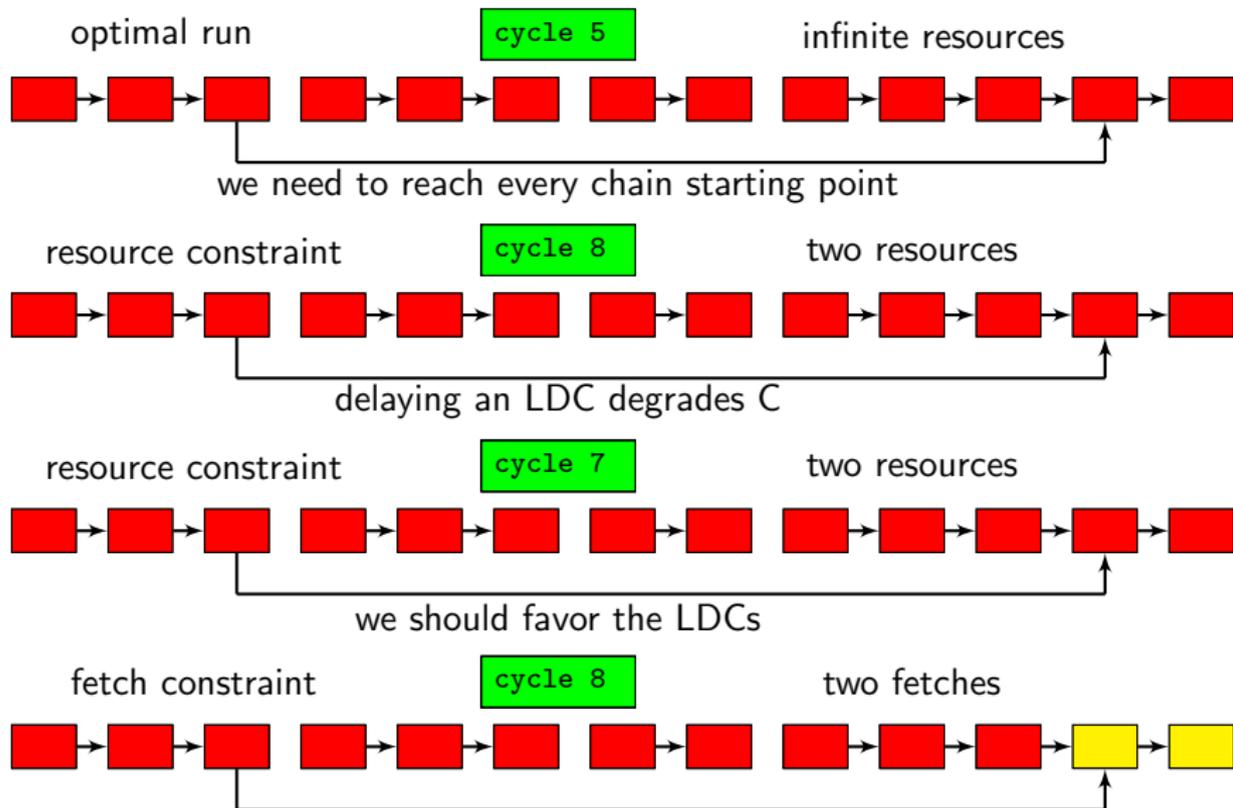
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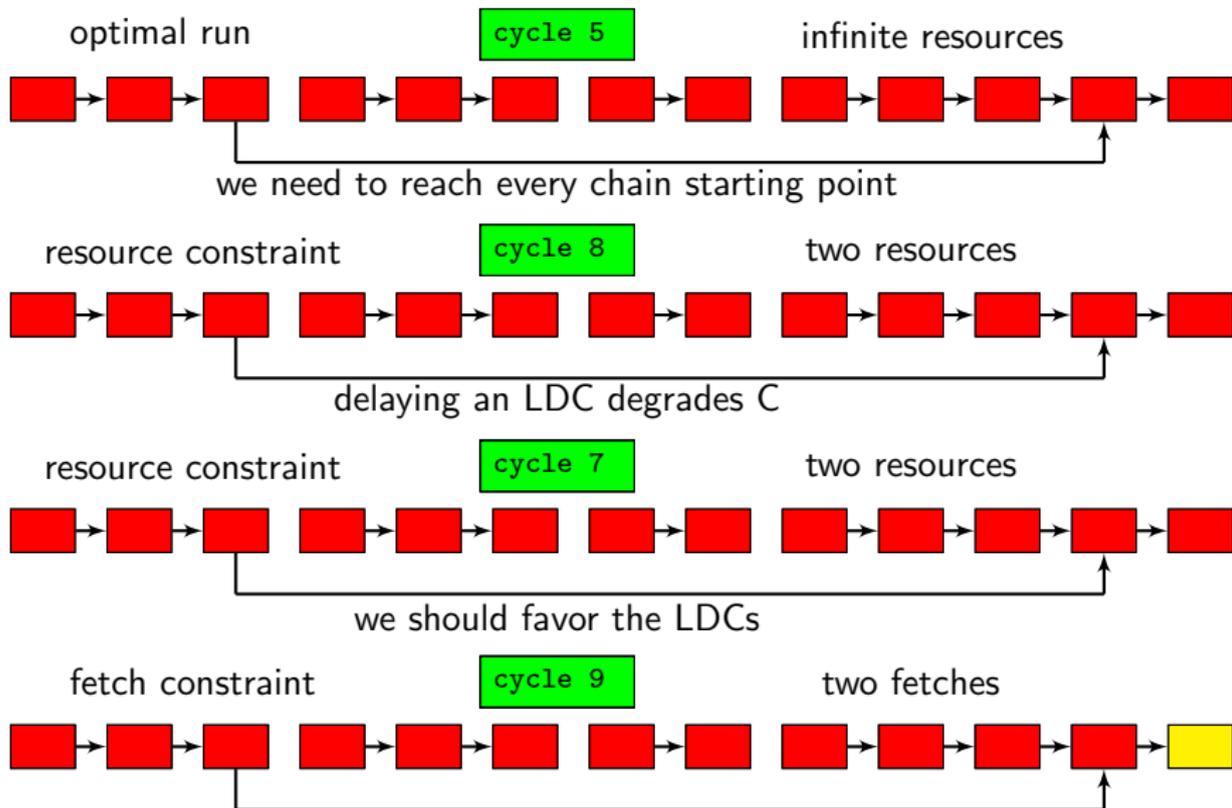
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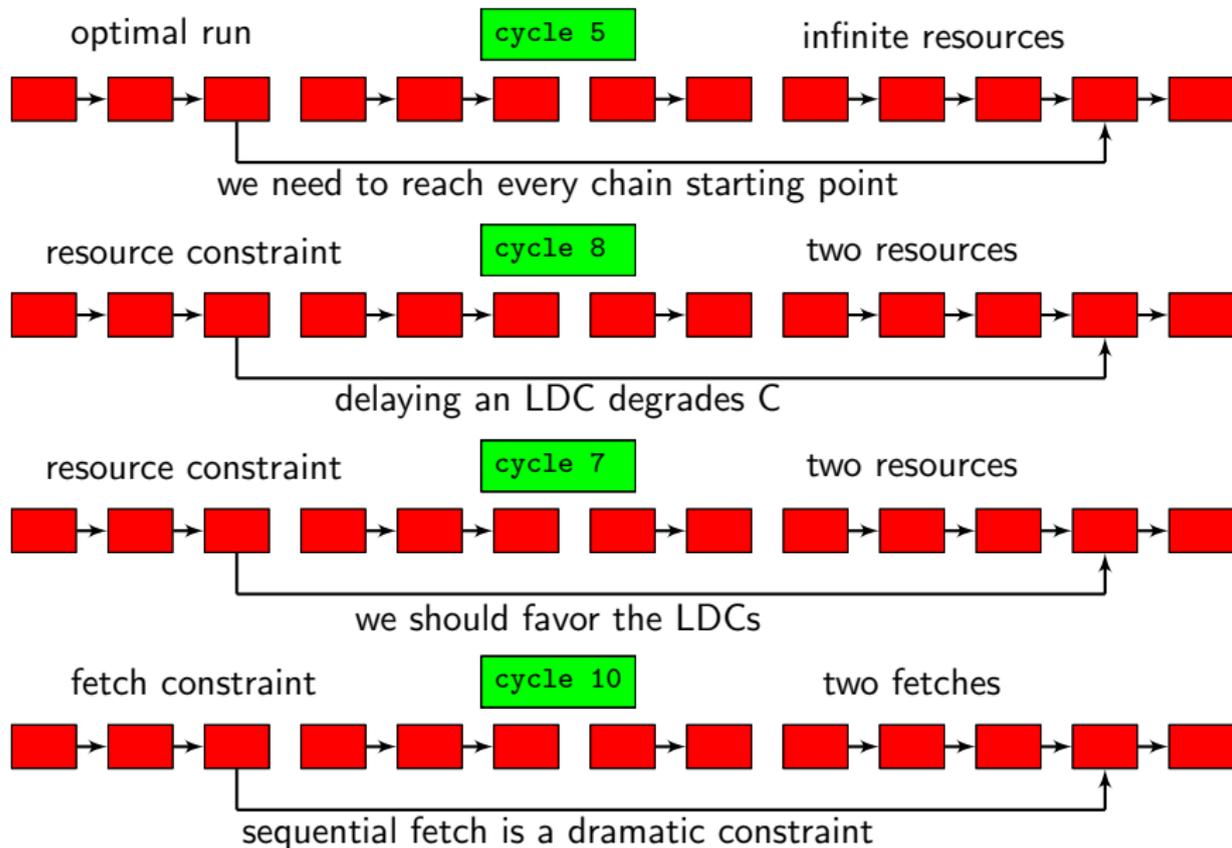
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- We must **rename dynamic memory** places.
- Memory renaming is ideal to **match producer/consumer dependent store/load** pairs and to **parallelize independent** accesses.

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- The test and conditional branch in the control **are delayed if the LIMIT is not a constant**.

## ILP in for loops.

```
//ILP = 3  
for (i=0; i<1024; i++){ //from cycle 1 to 1024, produce i  
    ... //from cycle 2 to 1025, test i  
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//ILP = 3
for (i=0; i<1024; i++){ //from cycle 1 to 1024, produce i
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//ILP =  $3n/(p+1) < 3$ 
//produce n at cycle p-1 > n
for (i=0; i<n; i++){ //from cycle 1 to n, produce i
    ... //at cycle p, 1024 tests of i
} //at cycle p+1, 1024 cond branch
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//ILP = 3
for (i=0; i<1024; i++){ //from cycle 1 to 1024, produce i
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} //at cycle p+1, 1024 cond branch

//ILP = 3n/(p+1) <3
//produce j at cycle q-1>n
//produce n at cycle p-1>q+1024
for (i=j; i<n; i++){ //from cycle q to q+1024, produce i
    ... //at cycle p, 1024 tests of i
} //at cycle p+1, 1024 cond branch
```

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//ILP = 3
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//ILP = 3n/(p+1) < 3
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for (i=0; i<n; i++){ //from cycle 1 to n, produce i
    ... //at cycle p, 1024 tests of i
} //at cycle p+1, 1024 cond branch

//ILP = 3n/(p+1) < 3
//produce j at cycle q-1 > n
//produce n at cycle p-1 > q+1024
for (i=j; i<n; i++){ //from cycle q to q+1024, produce i
    ... //at cycle p, 1024 tests of i
} //at cycle p+1, 1024 cond branch

//ILP = 3*1024
//nested loops are vectorized
for (i=0; i<1024; i++){ //from cycle 1 to 1024, produce i
    for (j=0; j<1024; j++){ //from cycle 1 to 1024, produce 1024 j
        ... //from cycle 2 to 1024, test 1024 j
    } //from cycle 3 to 1026, 1024 cond branch
    ... //from cycle 2 to 1024, test i
} //from cycle 3 to 1026, cond branch
```

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- The loop body should be built to allow a **maximum overlapping** of successive iterations (i.e. **one cycle shift**).
- The **body ILP is bounded** by the body instruction number. To increase the body ILP, **unroll the loop**.
- Loops controls are **often independent** and can be run in parallel.

## Nested loops.

```
...           ; x computed in al           x=f(...);
movl $0, %esi ; i=0                       for (i=0;i<1024;i++)
.L5:          ; external loop start        for (j=0;j<1024;j++)
movl $0, %edi ; j=0                       t[i][j]=x;
.L4:          ; internal loop start
movl %esi, %ecx ; ecx=i
sall $10, %ecx ; ecx=ecx*1024
addl %edi, %ecx ; ecx=ecx+j
movb %al, t(%ecx); t[i][j]=x
addl $1, %edi ; j++
cmpl $1024, %edi ; (j == 1024)
jne .L4      ; if (j!=1024) goto .L4
; internal loop end
addl $1, %esi ; i++
cmpl $1024, %esi ; (i == 1024)
jne .L5      ; if (i!=1024) goto .L5
; external loop end
```

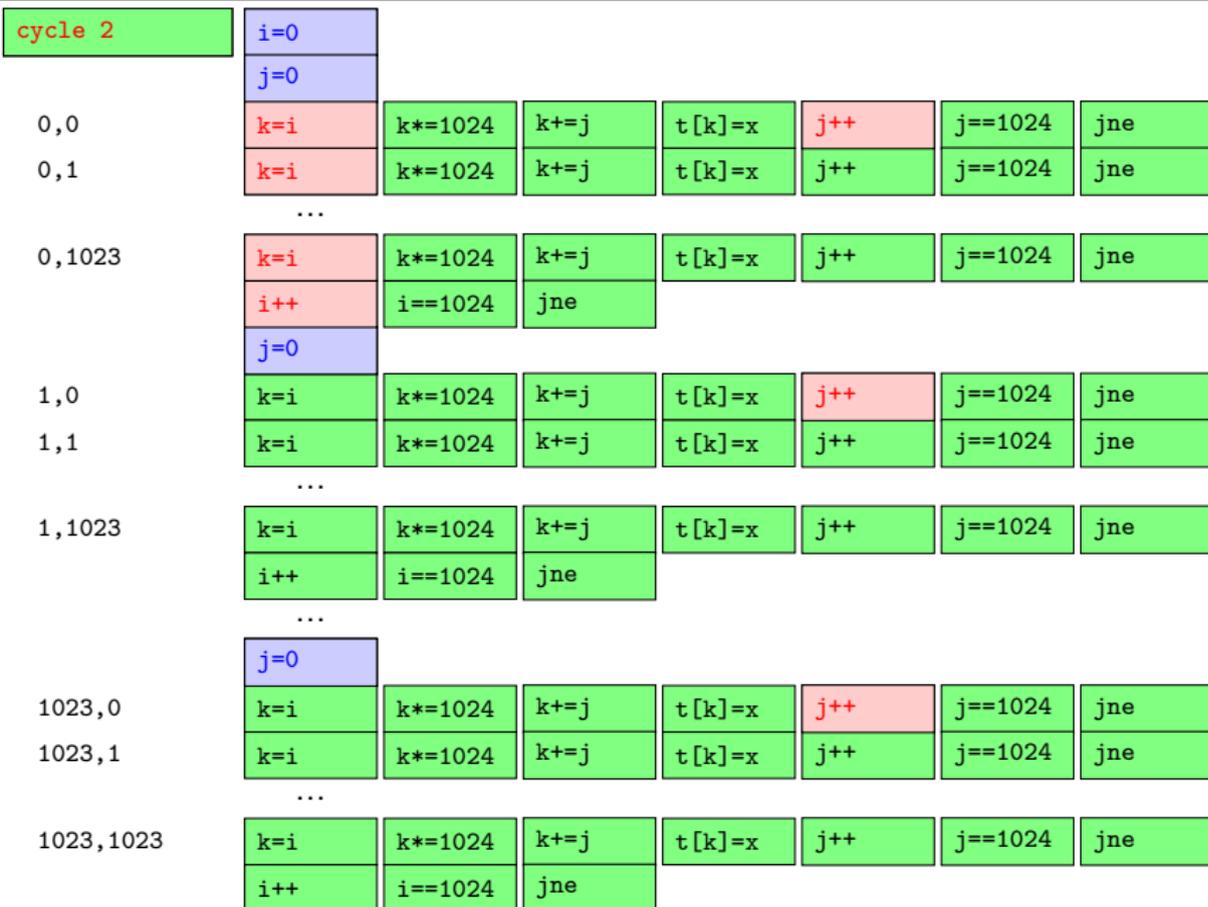
# Nested loops.

cycle 0		i=0						
		j=0						
0,0		k=i	k*=1024	k+=j	t[k]=x	j++	j==1024	jne
0,1		k=i	k*=1024	k+=j	t[k]=x	j++	j==1024	jne
		...						
0,1023		k=i	k*=1024	k+=j	t[k]=x	j++	j==1024	jne
		i++	i==1024	jne				
		j=0						
1,0		k=i	k*=1024	k+=j	t[k]=x	j++	j==1024	jne
1,1		k=i	k*=1024	k+=j	t[k]=x	j++	j==1024	jne
		...						
1,1023		k=i	k*=1024	k+=j	t[k]=x	j++	j==1024	jne
		i++	i==1024	jne				
		...						
		j=0						
1023,0		k=i	k*=1024	k+=j	t[k]=x	j++	j==1024	jne
1023,1		k=i	k*=1024	k+=j	t[k]=x	j++	j==1024	jne
		...						
1023,1023		k=i	k*=1024	k+=j	t[k]=x	j++	j==1024	jne
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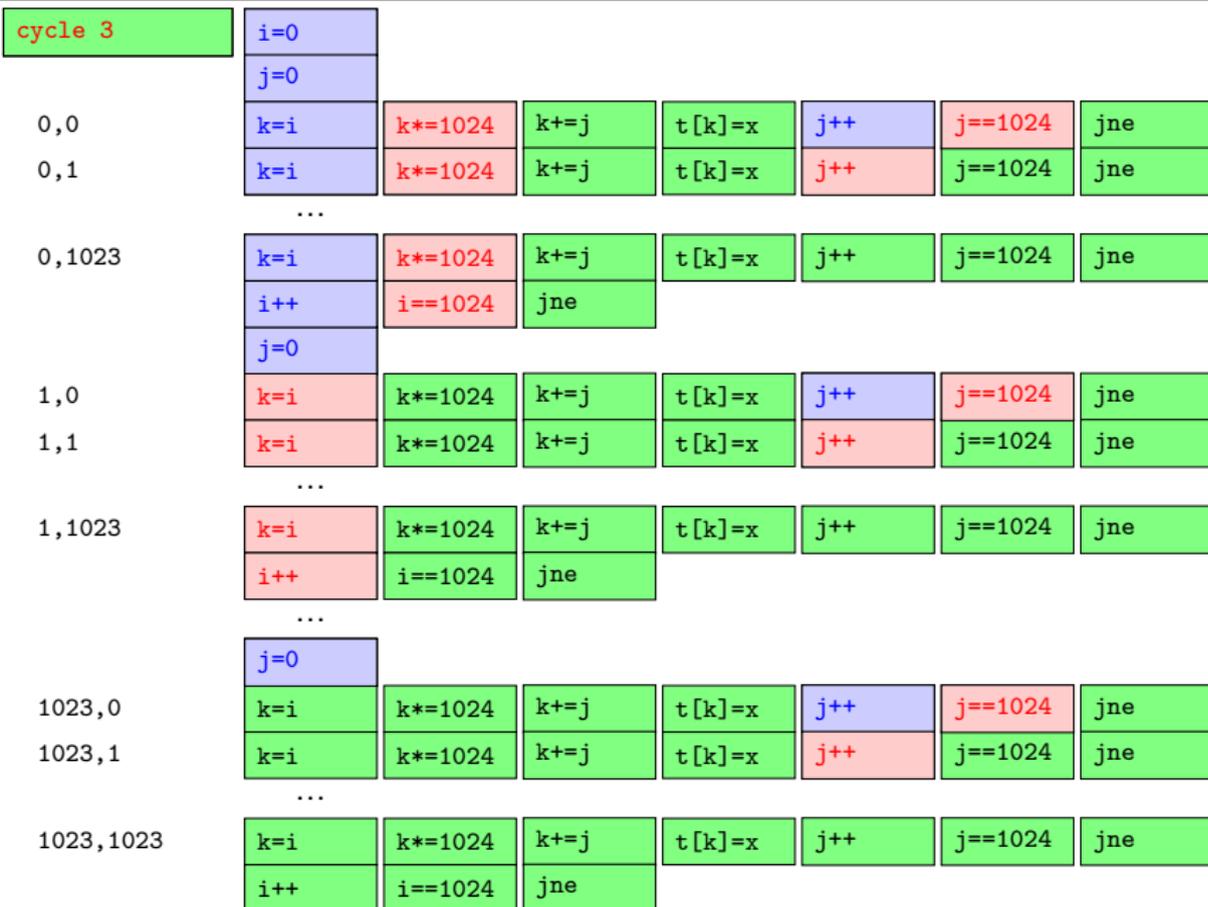
# Nested loops.

cycle 1		i=0						
		j=0						
0,0		k=i	k*=1024	k+=j	t[k]=x	j++	j==1024	jne
0,1		k=i	k*=1024	k+=j	t[k]=x	j++	j==1024	jne
		...						
0,1023		k=i	k*=1024	k+=j	t[k]=x	j++	j==1024	jne
		i++	i==1024	jne				
		j=0						
1,0		k=i	k*=1024	k+=j	t[k]=x	j++	j==1024	jne
1,1		k=i	k*=1024	k+=j	t[k]=x	j++	j==1024	jne
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1,1023		k=i	k*=1024	k+=j	t[k]=x	j++	j==1024	jne
		i++	i==1024	jne				
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1023,0		k=i	k*=1024	k+=j	t[k]=x	j++	j==1024	jne
1023,1		k=i	k*=1024	k+=j	t[k]=x	j++	j==1024	jne
		...						
1023,1023		k=i	k*=1024	k+=j	t[k]=x	j++	j==1024	jne
		i++	i==1024	jne				

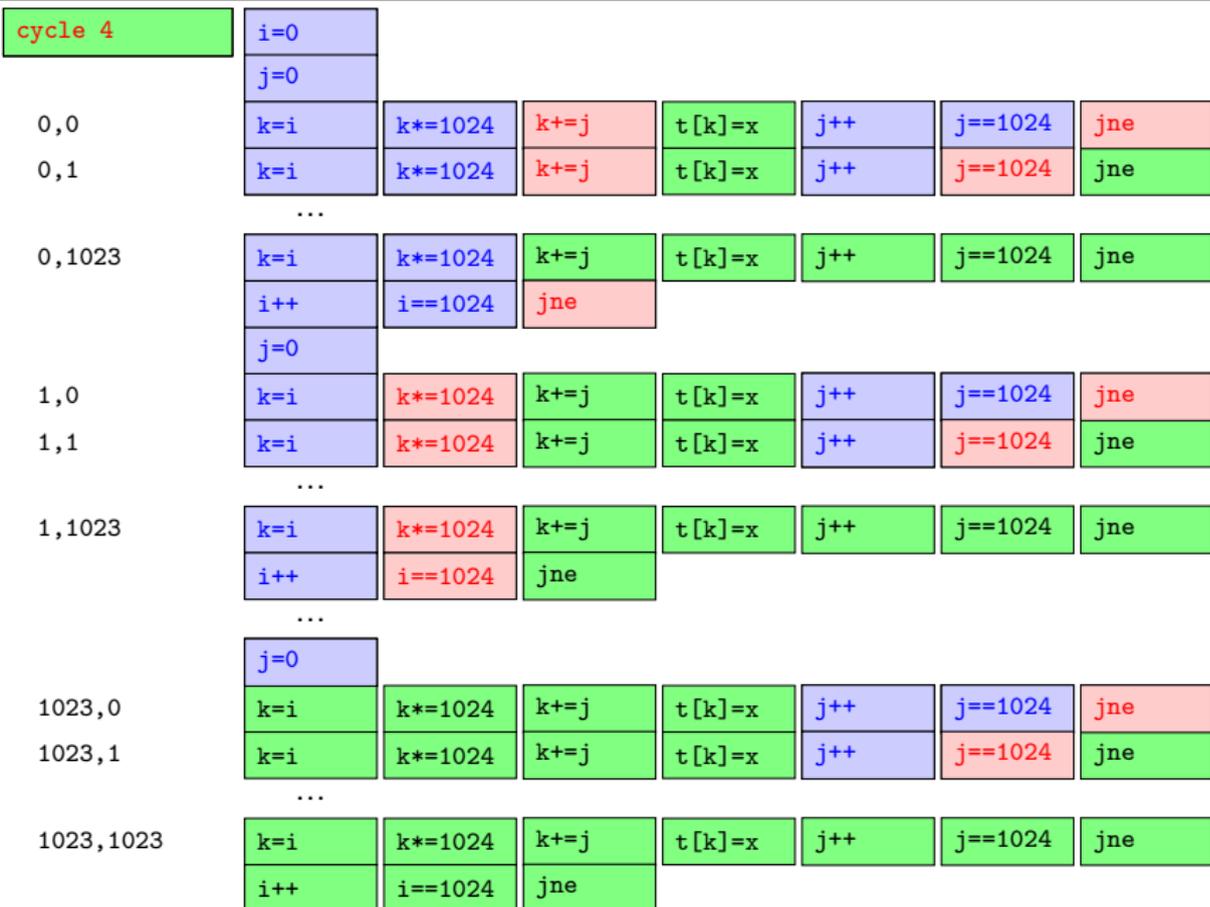
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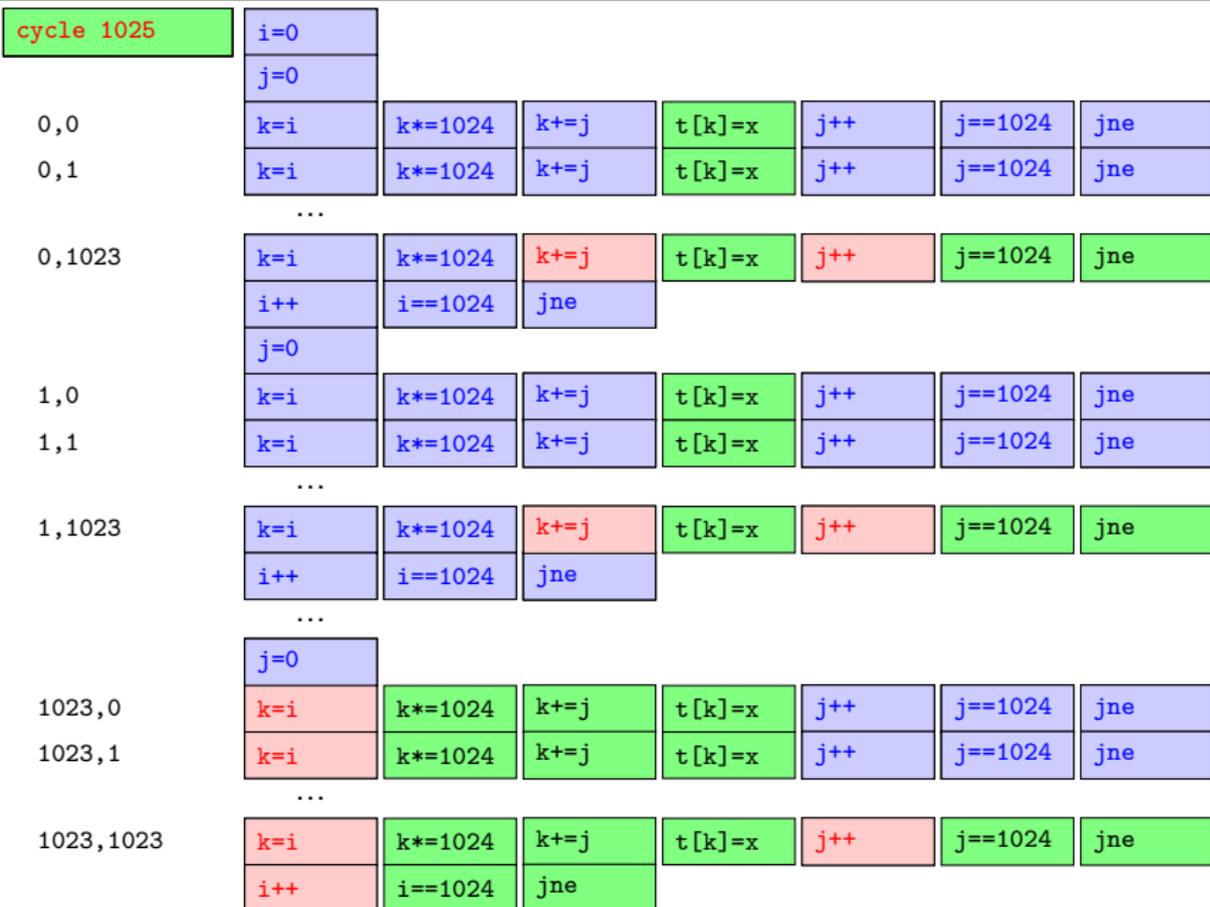
# Nested loops.

cycle 5		i=0						
		j=0						
0,0		k=i	k*=1024	k+=j	t[k]=x	j++	j==1024	jne
0,1		k=i	k*=1024	k+=j	t[k]=x	j++	j==1024	jne
		...						
0,1023		k=i	k*=1024	k+=j	t[k]=x	j++	j==1024	jne
		i++	i==1024	jne				
		j=0						
1,0		k=i	k*=1024	k+=j	t[k]=x	j++	j==1024	jne
1,1		k=i	k*=1024	k+=j	t[k]=x	j++	j==1024	jne
		...						
1,1023		k=i	k*=1024	k+=j	t[k]=x	j++	j==1024	jne
		i++	i==1024	jne				
		...						
		j=0						
1023,0		k=i	k*=1024	k+=j	t[k]=x	j++	j==1024	jne
1023,1		k=i	k*=1024	k+=j	t[k]=x	j++	j==1024	jne
		...						
1023,1023		k=i	k*=1024	k+=j	t[k]=x	j++	j==1024	jne
		i++	i==1024	jne				

# Nested loops.

cycle 6		i=0					
		j=0					
0,0		k=i	k*=1024	k+=j	t[k]=x	j++	j==1024 jne
0,1		k=i	k*=1024	k+=j	t[k]=x	j++	j==1024 jne
		...					
0,1023		k=i	k*=1024	k+=j	t[k]=x	j++	j==1024 jne
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		i++	i==1024	jne			

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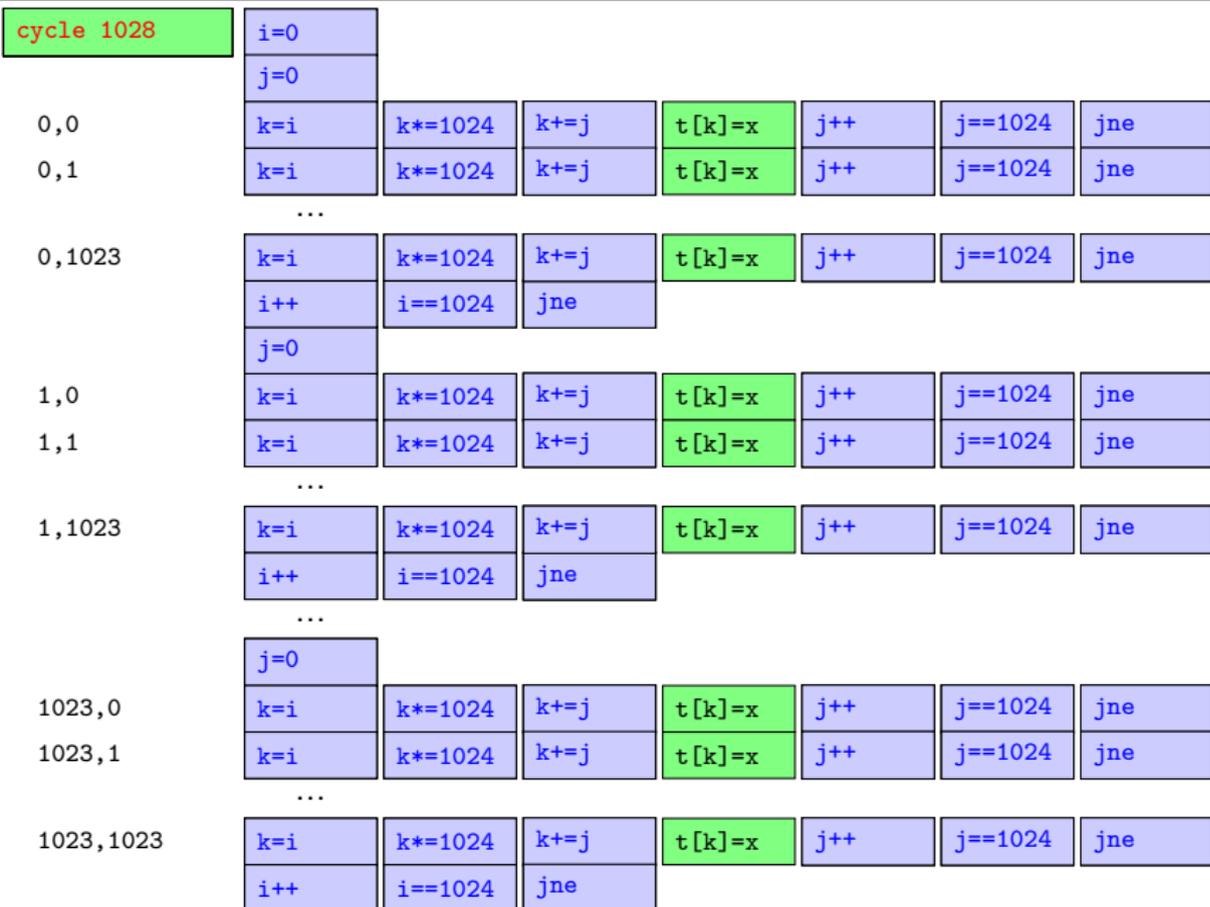
# Nested loops.

cycle 1026		i=0					
		j=0					
0,0		k=i	k*=1024	k+=j	t[k]=x	j++	j==1024 jne
0,1		k=i	k*=1024	k+=j	t[k]=x	j++	j==1024 jne
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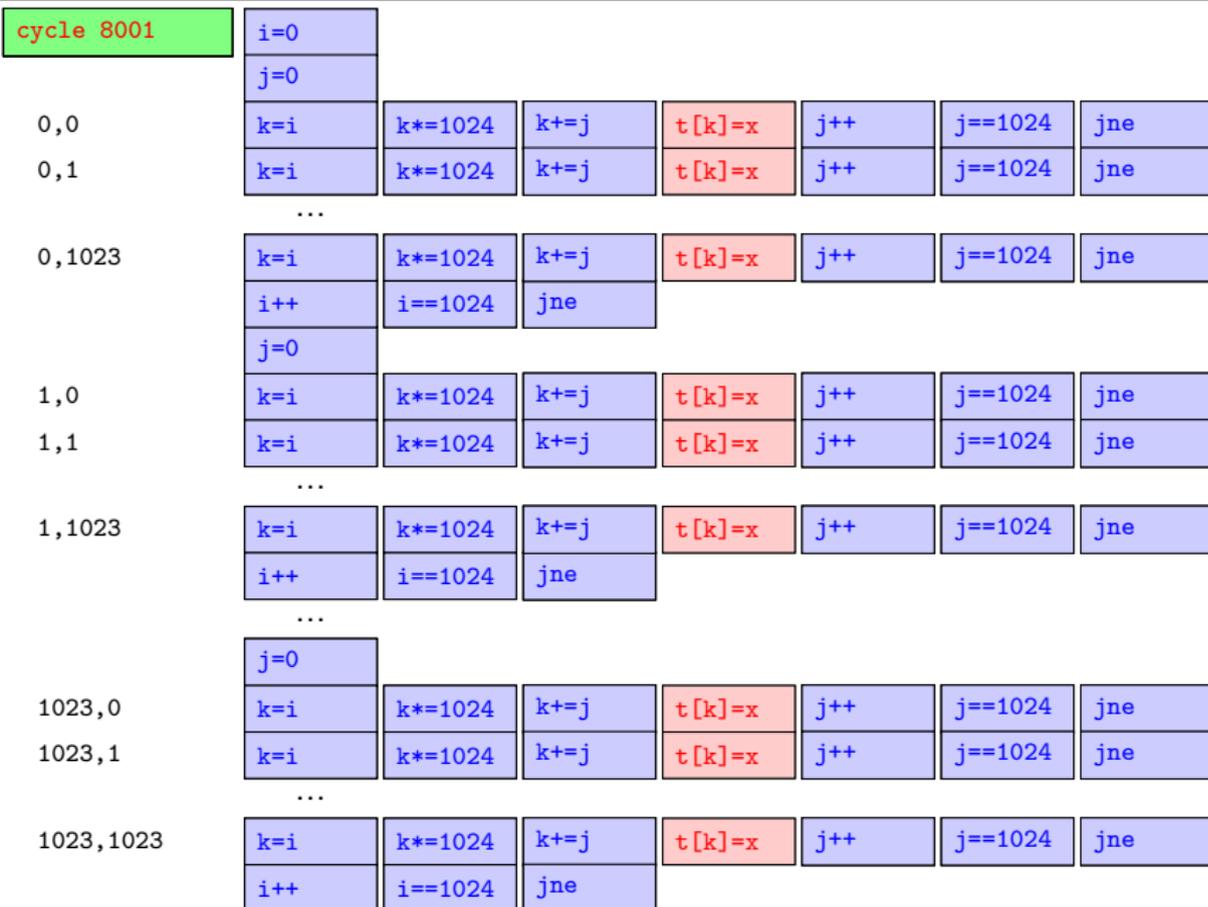
# Nested loops.

cycle 1027		i=0					
		j=0					
0,0		k=i	k*=1024	k+=j	t[k]=x	j++	j==1024 jne
0,1		k=i	k*=1024	k+=j	t[k]=x	j++	j==1024 jne
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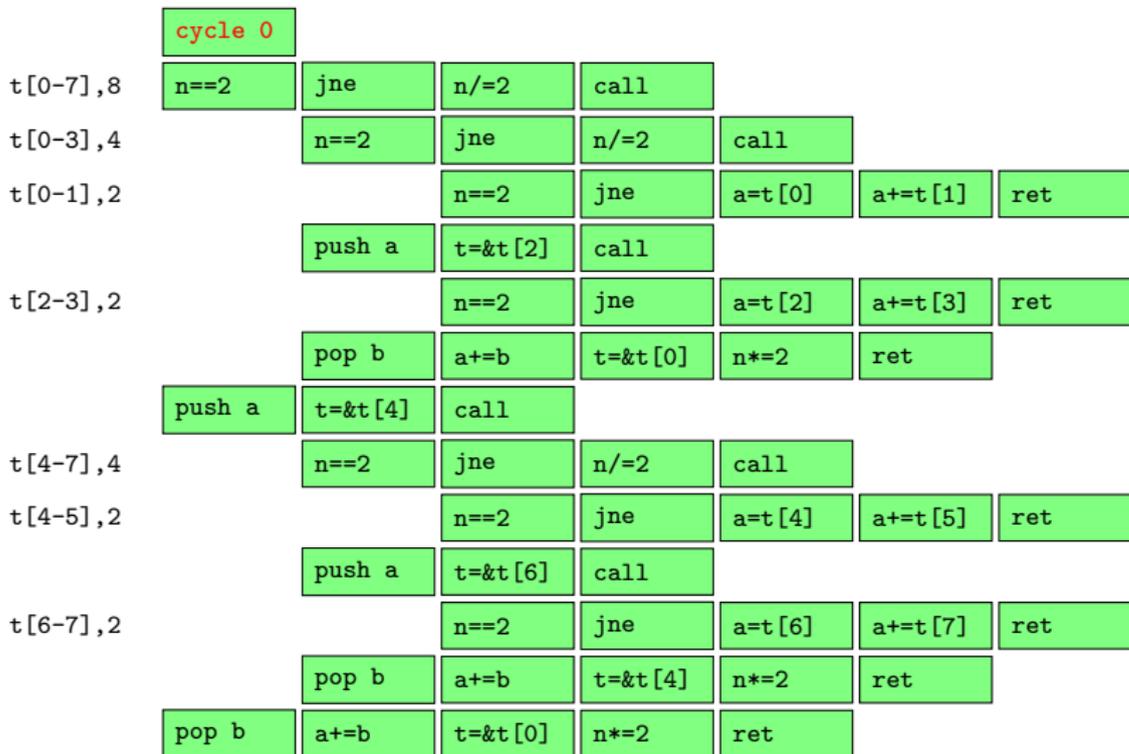
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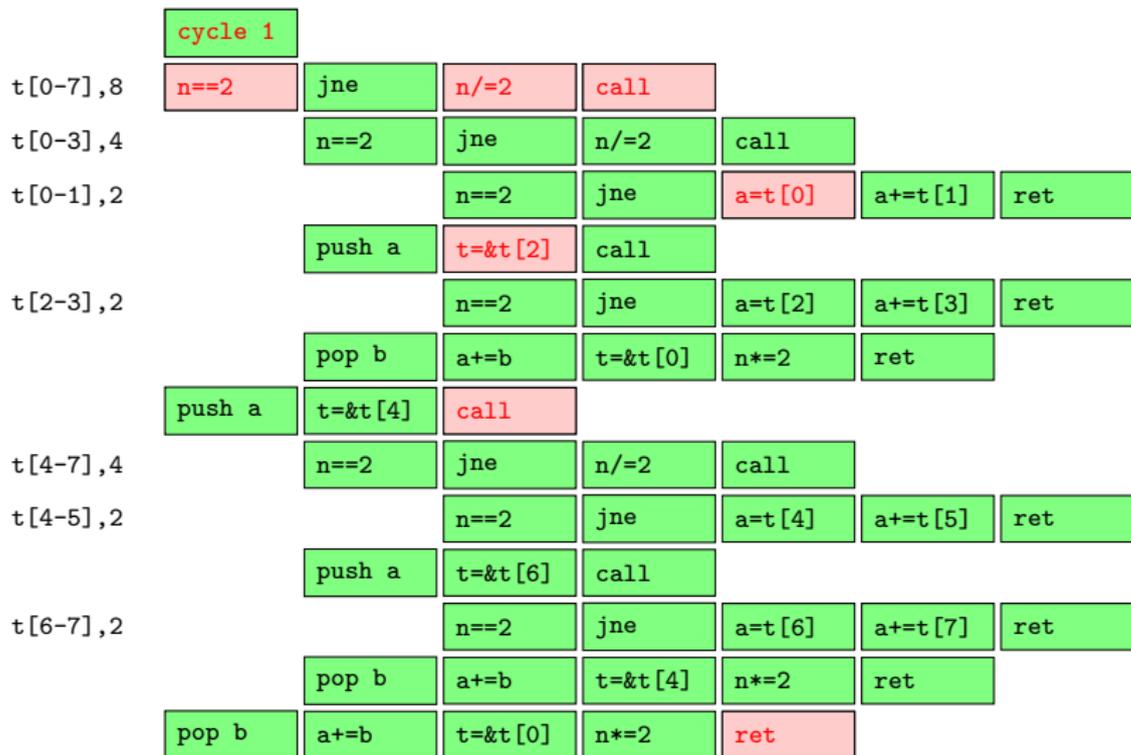
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- Functions controls are **often independent** and can be run in parallel.

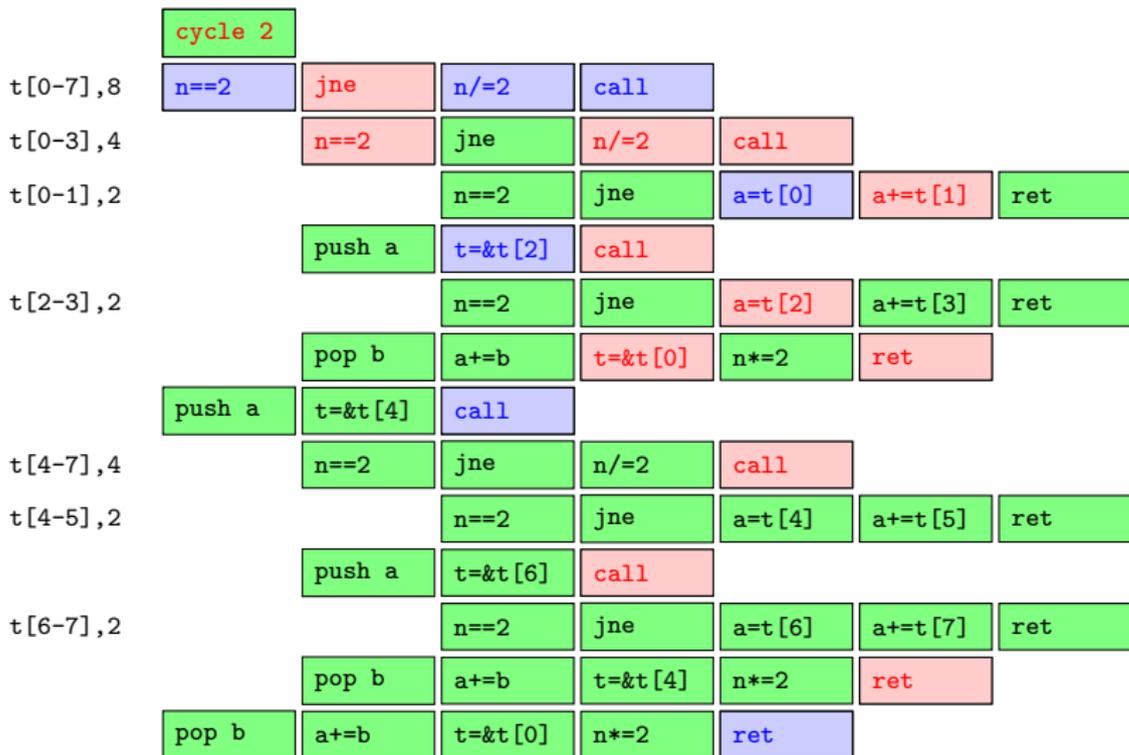
# Running `sum_reduce(t[0,7],8)` in parallel.



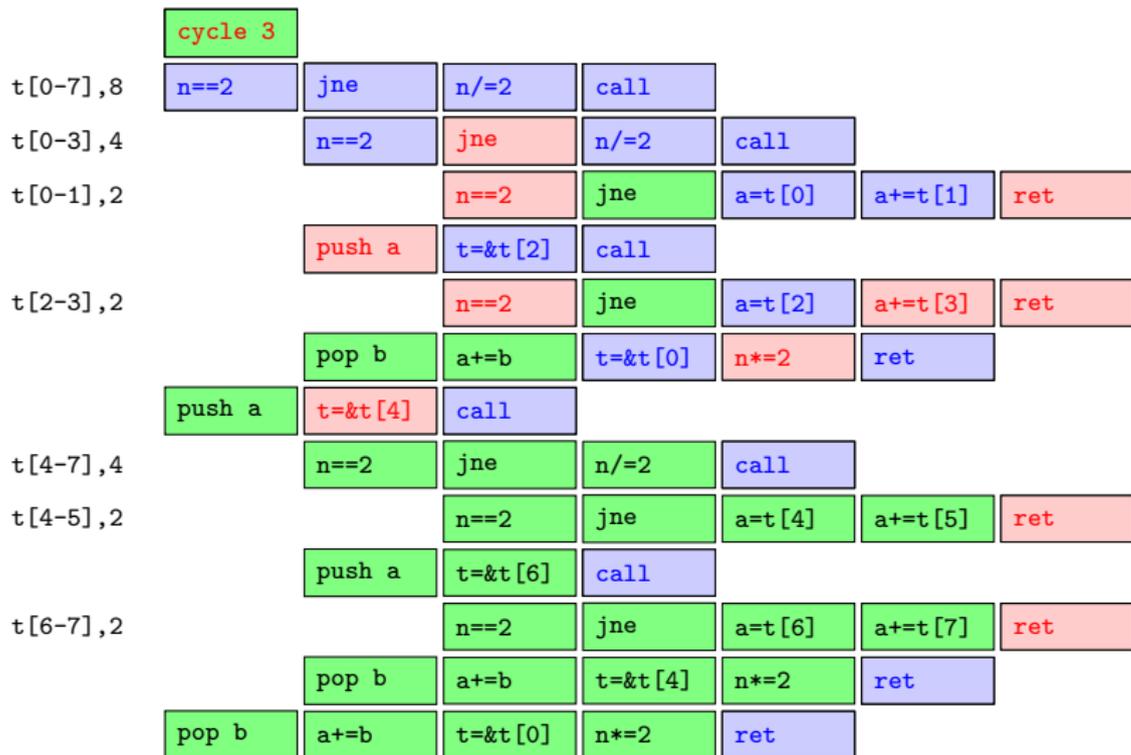
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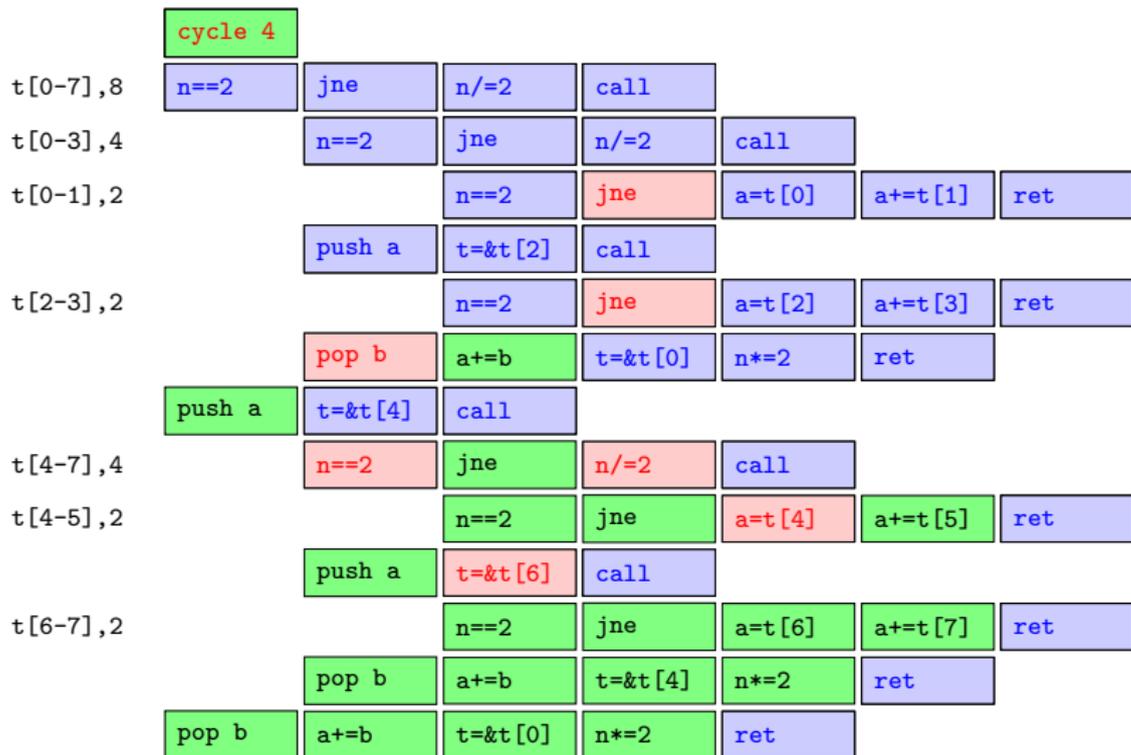
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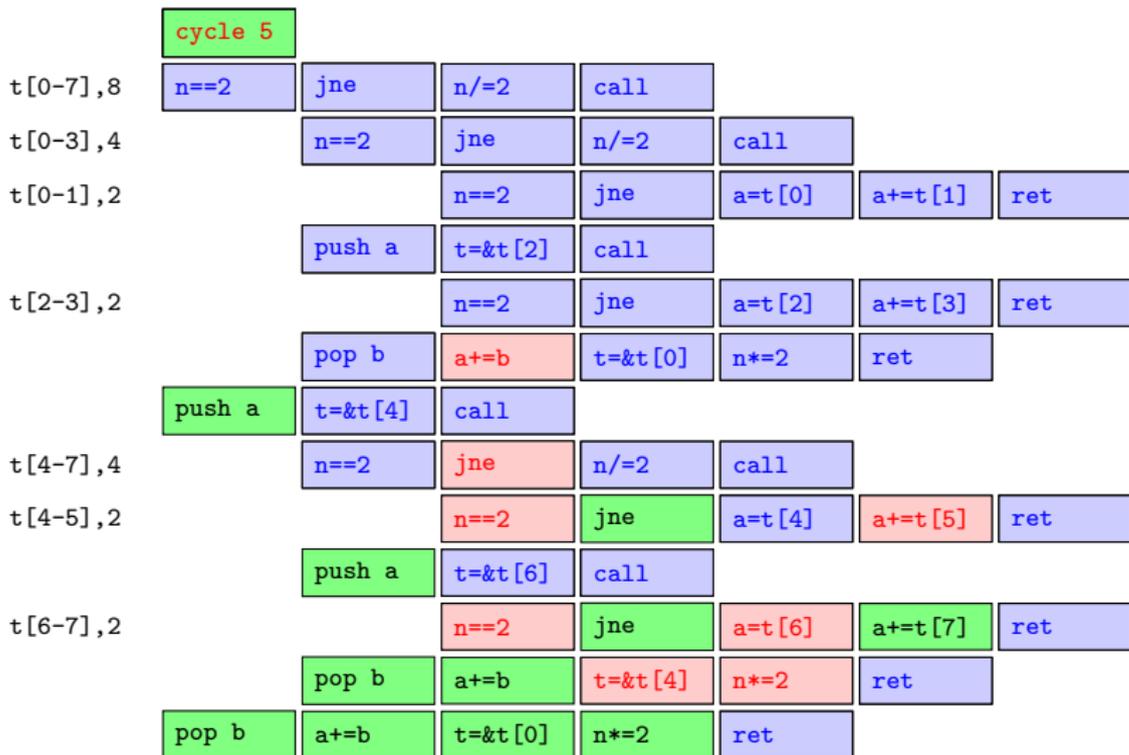
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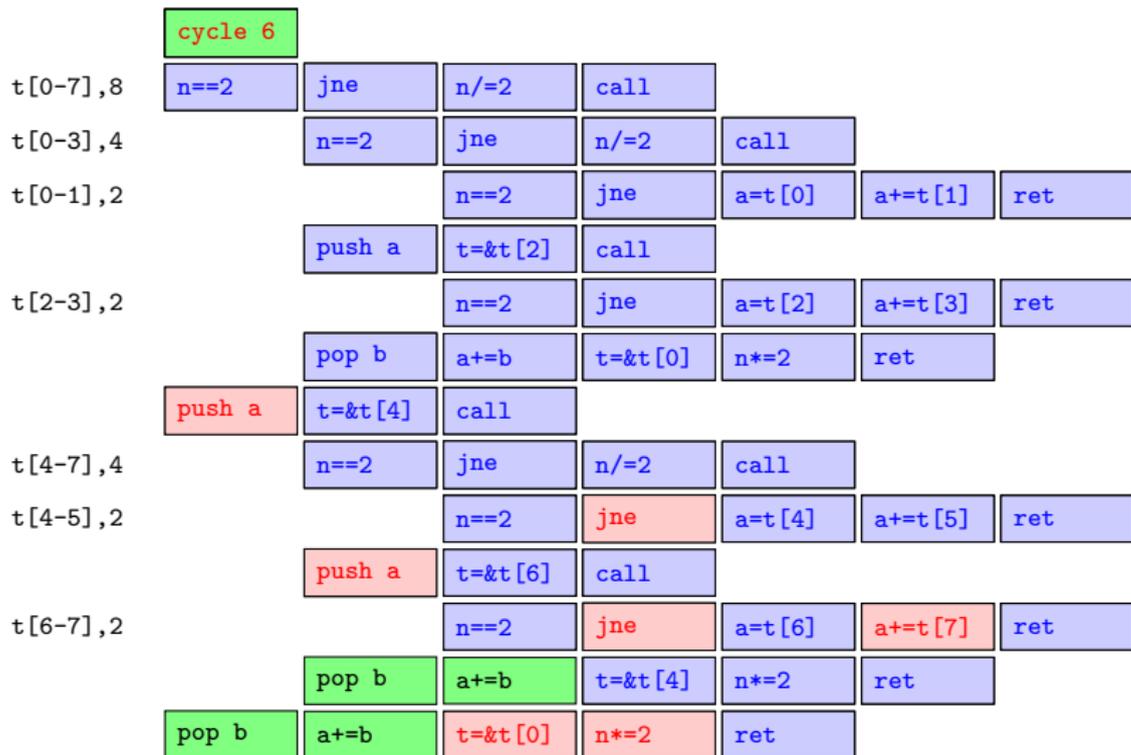
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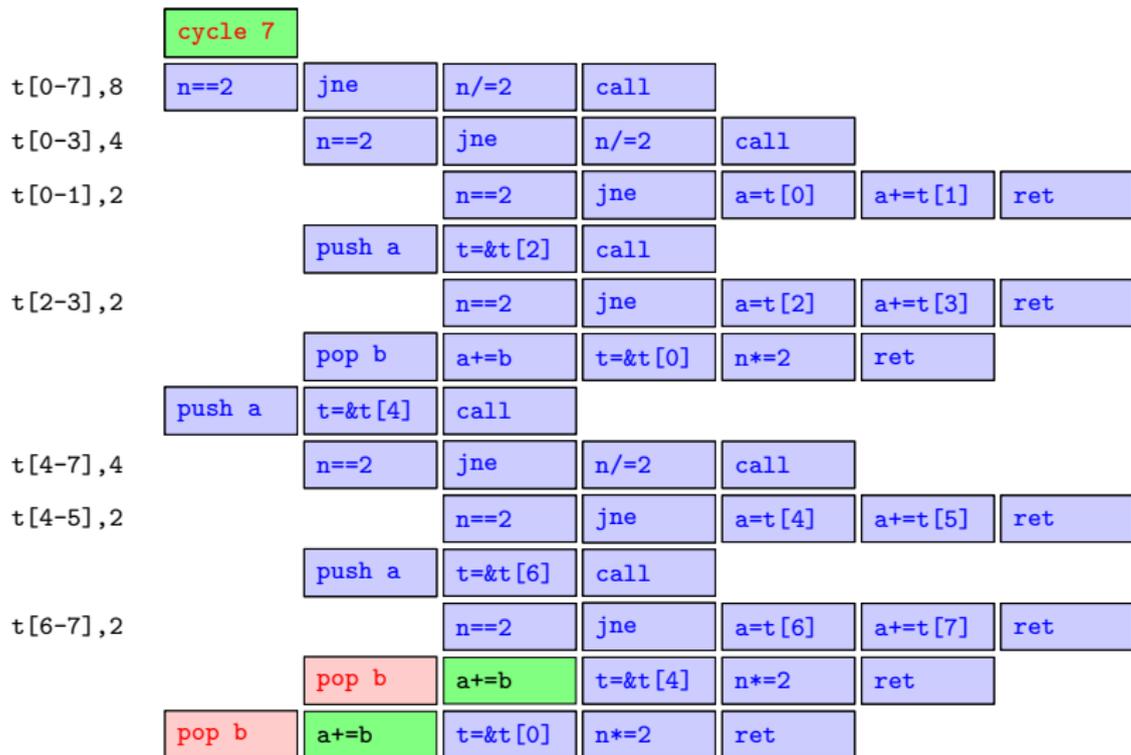
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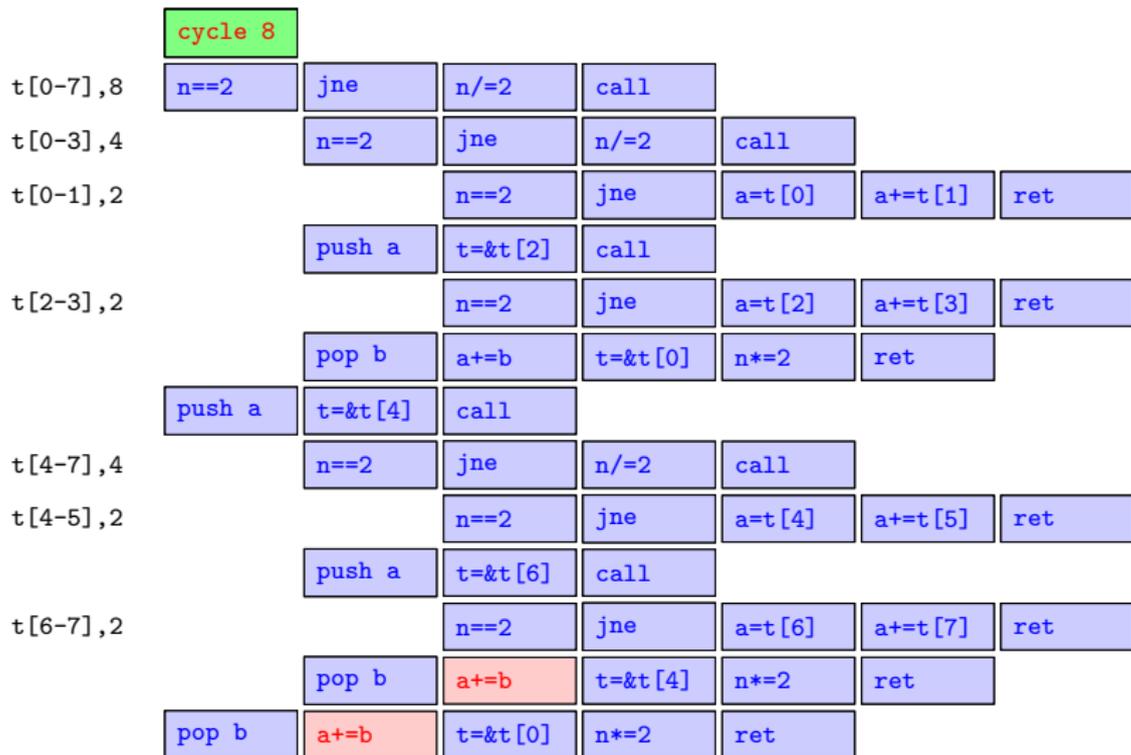
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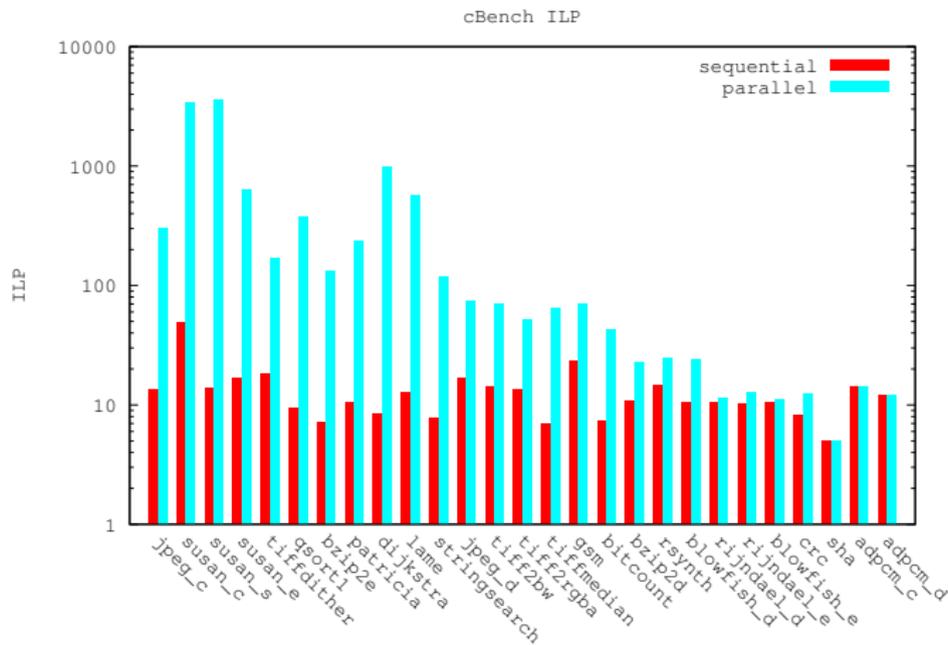
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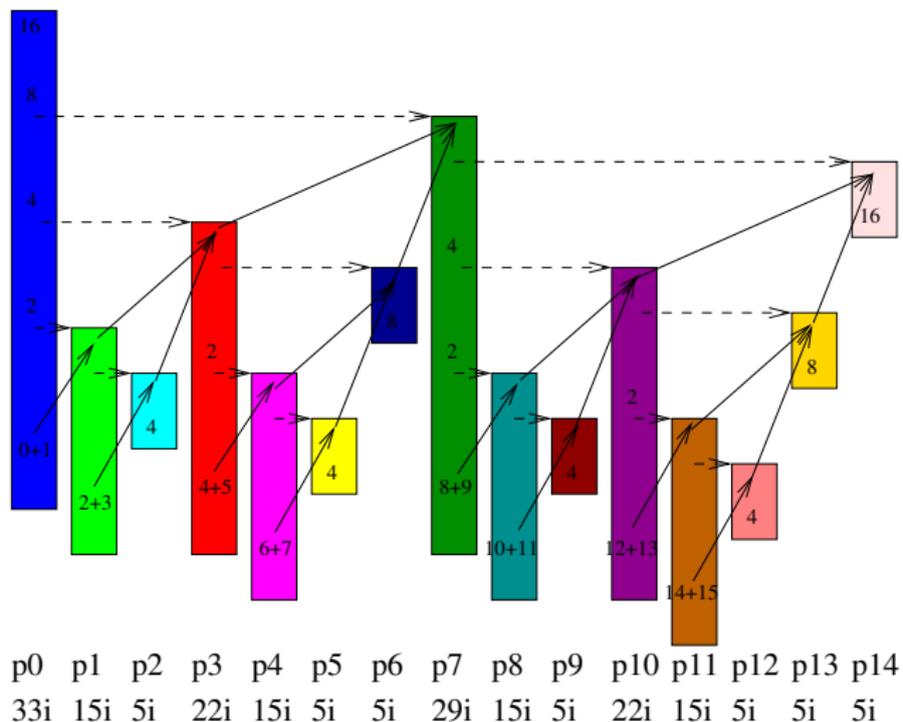
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- Optionally, by **renaming constants** we can precompute loop control at rename phase to allow **vectorization at run phase**.

# Impact de la parallélisation de l'extraction, du renommage et de l'exécution.

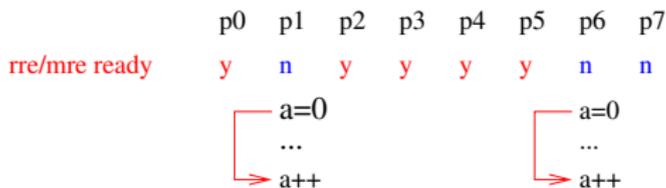


# Le modèle d'exécution parallèle appliqué à `sum_reduce(t,16)`.

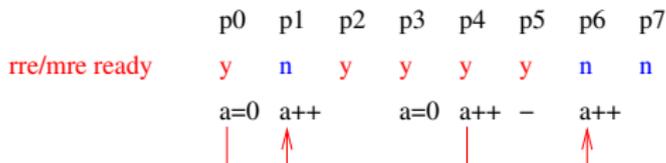


# Le renommage en parallèle.

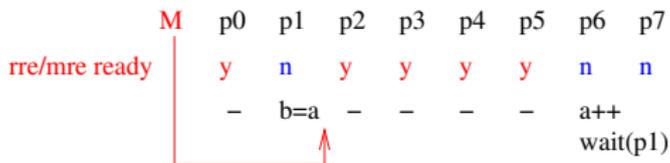
(a) parallel local imports



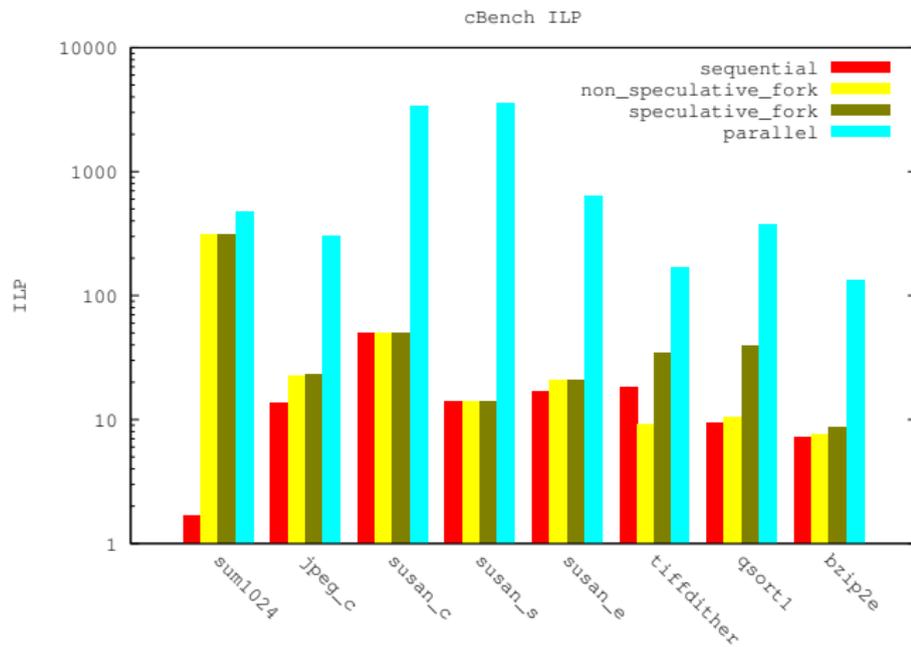
(b) parallel global imports



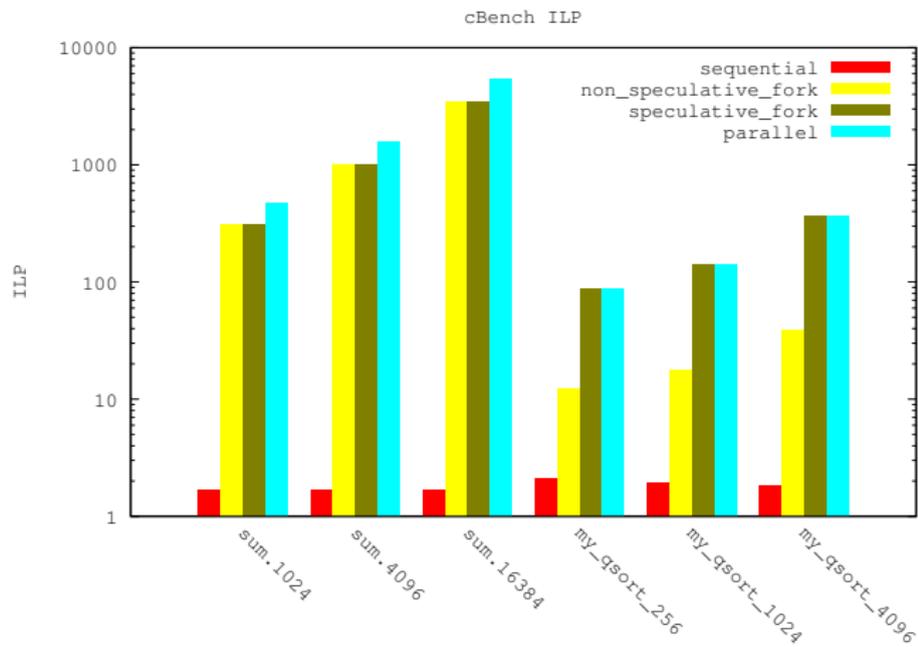
(c) memory import and import wait



# La capture d'ILP avec fork spéculatif et non spéculatif.



# La capture d'ILP sur deux algorithmes parallèles.



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- This fast forwarding feeds the cores with **independent instructions**.
- **No need to rewrite the C version** of the algorithm which can be interpreted as parallel.
- What we usually call **sequential programs** contain **a lot of parallelism** unless the algorithms they come from **are themselves sequential**.